

Bioengineering 280A  
Principles of Biomedical Imaging

Fall Quarter 2005  
MRI Lecture 6

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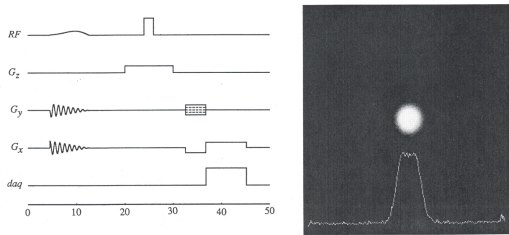
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Excitation k-space



Pauly et al 1989

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Moving Spins

So far we have assumed that the spins are not moving (aside from thermal motion giving rise to relaxation), and contrast has been based upon  $T_1$ ,  $T_2$ , and proton density. We were able to achieve different contrasts by adjusting the appropriate pulse sequence parameters.

Biological samples are filled with moving spins, and we can also use MRI to image the movement. Examples: blood flow, diffusion of water in the white matter tracts. In addition, we can also sometimes induce motion into the object to image its mechanical properties, e.g. imaging of stress and strain with MR elastography.

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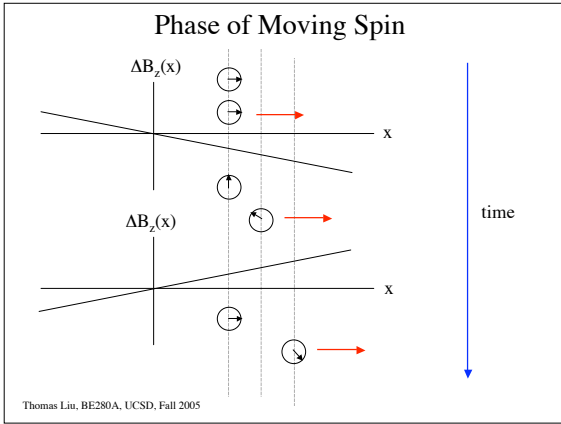
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### Phase of a Moving Spin

$$\begin{aligned} \varphi(t) &= -\int_0^t \Delta\omega(\tau) d\tau \\ &= -\int_0^t \gamma \Delta B(\tau) d\tau \\ &= -\int_0^t \gamma \vec{G}(\tau) \cdot \vec{r}(\tau) d\tau \\ &= -\gamma \int_0^t [G_x(\tau)x(\tau) + G_y(\tau)y(\tau) + G_z(\tau)z(\tau)] d\tau \end{aligned}$$

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### Phase of Moving Spin

Consider motion along the x-axis

$$x(t) = x_0 + vt + \frac{1}{2}at^2$$

$$\begin{aligned} \varphi(t) &= -\gamma \int_0^t G_x(\tau)x(\tau) d\tau \\ &= -\gamma \int_0^t G_x(\tau) \left[ x_0 + v\tau + \frac{1}{2}a\tau^2 \right] d\tau \\ &= -\gamma \left[ x_0 \int_0^t G_x(\tau) d\tau + v \int_0^t G_x(\tau) \tau d\tau + \frac{a}{2} \int_0^t G_x(\tau) \tau^2 d\tau \right] \\ &= -\gamma \left[ x_0 M_0 + v M_1 + \frac{a}{2} M_2 \right] \end{aligned}$$

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### Phase of Moving Spin

$$\varphi(t) = -\gamma \left[ x_0 M_0 + v M_1 + \frac{a}{2} M_2 \right]$$

$$M_0 = \int_0^T G_x(\tau) d\tau \quad \text{Zeroth order moment}$$

$$M_1 = \int_0^T G_x(\tau) \tau d\tau \quad \text{First order moment}$$

$$M_2 = \int_0^T G_x(\tau) \tau^2 d\tau \quad \text{Second order moment}$$

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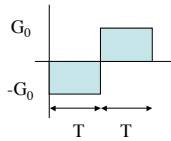
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### Flow Moment Example



$$M_0 = \int_0^T G_x(\tau) d\tau = 0$$

$$\begin{aligned} M_1 &= \int_0^T G_x(\tau) \tau d\tau \\ &= -\int_0^T G_0 \tau d\tau + \int_T^{2T} G_0 \tau d\tau \\ &= G_0 \left[ -\frac{\tau^2}{2} \Big|_0^T + \frac{\tau^2}{2} \Big|_T^{2T} \right] \\ &= G_0 \left[ -\frac{T^2}{2} + \frac{4T^2}{2} - \frac{T^2}{2} \right] = G_0 T^2 \end{aligned}$$

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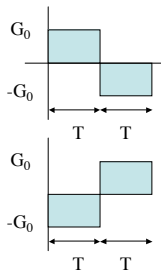
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### Phase Contrast Angiography (PCA)



$$\varphi_1 = -\gamma v_x M_1 = \gamma v_x G_0 T^2$$

$$\varphi_2 = -\gamma v_x M_1 = -\gamma v_x G_0 T^2$$

$$\Delta\varphi = \varphi_1 - \varphi_2 = 2\gamma v_x G_0 T^2$$

$$v_x = \frac{\Delta\varphi}{2G_0 T^2}$$

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### PCA example

-G<sub>0</sub>

White = Flow direction AP (↓)      White = Flow direction RL (→)  
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### Aliasing in PCA

Define VENC as the velocity at at which the phase is 180 degrees.

$$VENC = \frac{\pi}{\gamma G_0 T^2}$$

Because of phase wrapping the velocity of spins flowing faster than VENC is ambiguous.

+π at VENC

-π at -VENC

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### Aliasing Solutions

Use data from regions with slower flow

Use multiple VENC values so that the phase differences are smaller than π radians.

$$\varphi_1 = \pi \frac{v_x}{VENC_1}$$

$$\varphi_2 = \pi \frac{v_x}{VENC_2}$$

$$\varphi_1 - \varphi_2 = \pi v_x \left( \frac{1}{VENC_1} - \frac{1}{VENC_2} \right)$$

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### Velocity k-space

A bipolar gradient introduces a phase modulation across velocities of the form  $\varphi(v_x) = -\gamma v_x G_0 T^2$

We can make measurements with different amounts of phase modulation and then integrate over velocities to obtain

$$\begin{aligned}
 M(k_{v_x}) &= \int_{-\infty}^{\infty} m(v_x) e^{j\varphi(v_x)} dv_x \\
 &= \int_{-\infty}^{\infty} m(v_x) e^{-j\gamma v_x G_0 T^2} dv_x \\
 &= \int_{-\infty}^{\infty} m(v_x) e^{-j2\pi k_{v_x} v_x} dv_x \\
 &= F[m(v_x)] \text{ with } k_{v_x} = \frac{\gamma}{2\pi} G_0 T^2
 \end{aligned}$$

By making measurements with bipolar gradients of varying amplitudes/durations and taking the inverse transform of the measurements, we can obtain the velocity distribution.

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### Velocity k-space

$$M(k_x, k_{v_x}) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} m(x, v_x) e^{-j2\pi k_x x} e^{-j2\pi k_{v_x} v_x} dx dv_x$$

In addition, we can apply imaging gradients so that we can eventually obtain the velocity distribution at each point in space. A full k-space acquisition would then yield 6 dimensions -- 3 spatial dimensions and 3 velocity dimensions.

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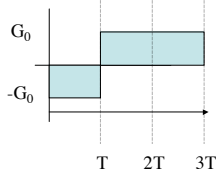
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### Readout Gradient Flow Artifacts



During readout moving spins within the object will accumulate phase that is in addition to the phase used for imaging. This leads to

- 1) Net phase at echo time TE = 2T.
- 2) An apparent shift in position of the object.
- 3) Blurring of the object due to a quadratic phase term.

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## Flow Artifacts

### Plug Flow



All moving spins in the voxel experience the same phase shift at echo time.

### Laminar Flow



Spins have different phase shifts at echo time. The dephasing causes the cancellation and signal dropout.

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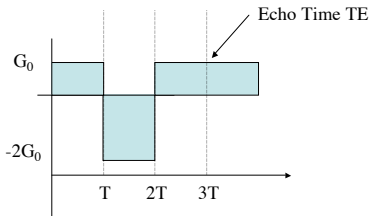
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## Flow Compensation

### Readout Gradient



At TE both the first and second order moments are zero, so both stationary and moving spins have zero net phase.

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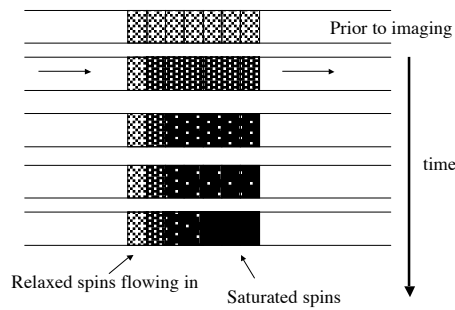
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## Inflow Effect



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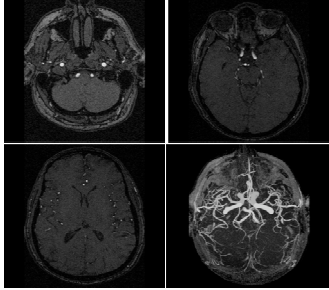
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### Time of Flight Angiography



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### Cerebral Blood Flow (CBF)

CBF = Perfusion  
 = Rate of delivery of arterial blood to a capillary bed in tissue.

Units:  $\frac{\text{(ml of Blood)}}{\text{(100 grams of tissue)(minute)}}$

Typical value is 60 ml/(100g-min) or 60 ml/(100 ml-min) = 0.01 s<sup>-1</sup>, assuming average density of brain equals 1 gm/ml

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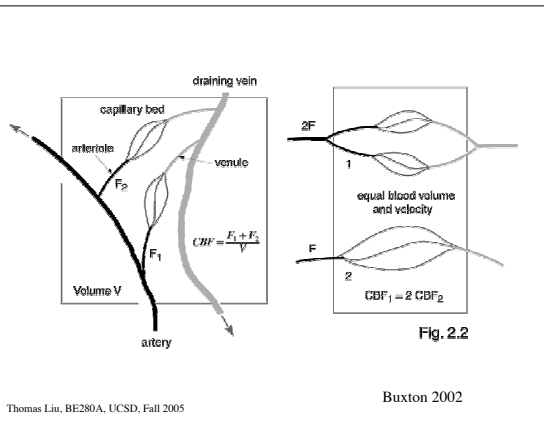
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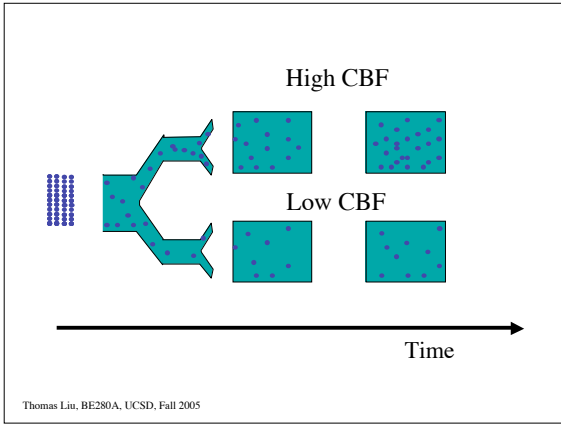
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### Arterial Spin Labeling

- Magnetically tag inflowing arterial blood
- Wait for tagged blood to flow into imaging slice
- Acquire image of tissue+tagged blood
- Apply control pulse that doesn't tag blood
- Acquire control image of tissue
- Control image-tag image = blood image

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### Arterial Spin Labeling (ASL)

1: Tag by Magnetic Inversion → Wait → Acquire image

2: Control → Wait → Acquire image

Control - Tag  $\propto$  CBF

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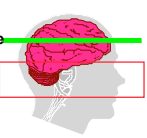
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### Arterial Spin Labeling (ASL)

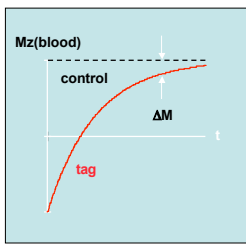
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- water protons as freely diffusible tracers

imaging slice



alternative inversion



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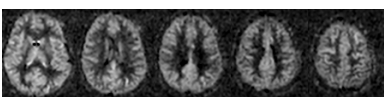
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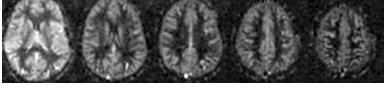
### Multislice CASL and PICORE

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CASL



PICORE  
QUIPSS II



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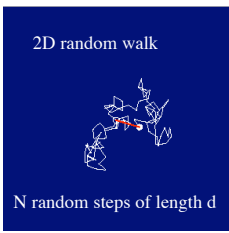
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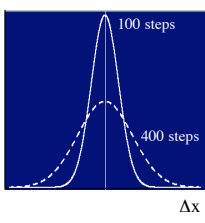
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### Diffusion

2D random walk



N random steps of length d



Δx

$\langle \Delta x^2 \rangle = Nd^2 = 2DT$

D = diffusivity

In brain:  
 $D \approx 0.001 \text{ mm}^2/\text{s}$   
 For  $T=100 \text{ msec}$ ,  
 $\Delta x \approx 15 \mu$

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### Diffusion Weighting

Assume  $\delta \ll T$

$\varphi(t_1) \approx -\gamma G_0 x(t_1) \delta$

$\varphi(t_2) \approx +\gamma G_0 x(t_2) \delta$

Net Phase  $T$

$$\varphi \approx \varphi(t_1) + \varphi(t_2) = \gamma G_0 [x(t_2) - x(t_1)] \delta = \gamma G_0 \Delta x \delta$$

Average Squared Phase

$$\langle \varphi^2 \rangle = \gamma^2 G_0^2 \delta^2 \langle (\Delta x)^2 \rangle = \gamma^2 G_0^2 \delta^2 2DT$$

Signal

$$S \propto e^{\langle \varphi^2 \rangle / 2} = e^{-\gamma^2 G_0^2 \delta^2 DT} = e^{-bD}$$

b-factor  $\leftarrow$

A more careful analysis yields  $b = \gamma^2 G_0^2 \delta^2 (T - \delta/3)$

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### Diffusion Weighted Images

T2 weighted

Diffusion Weighted

Angiogram

After a stroke, normal water movement is restricted in the region of damage. Diffusivity decreases, so the signal intensity increases.

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[http://lehighmri.com/cases/dwi/patient\\_b.html](http://lehighmri.com/cases/dwi/patient_b.html)

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### Restricted Diffusion

D depends on direction

Diffusion tensor:  
3 values of D  
3 angles

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Credit: Larry Frank

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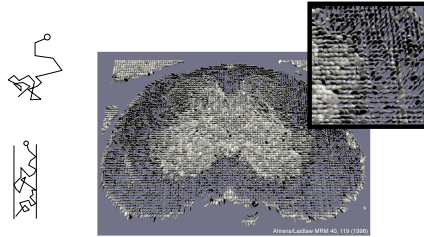
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### Diffusion Imaging Example



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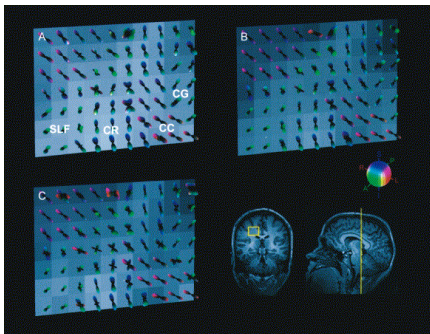
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### Q-ball imaging



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Tuch et al, Neuron 2003

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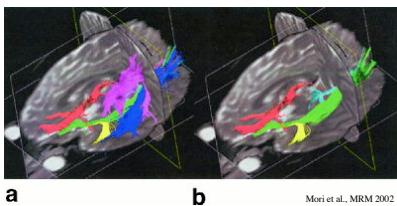
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### Fiber Tract Mapping



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Mori et al., MRM 2002

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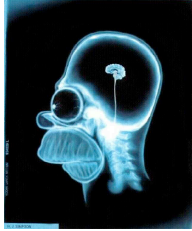
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## fMRI

MRI studies brain anatomy.



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Functional MRI (fMRI) studies brain function.



[http://defiant.ssc.uwo.ca/Jody\\_web/fmri4dummies.htm](http://defiant.ssc.uwo.ca/Jody_web/fmri4dummies.htm)

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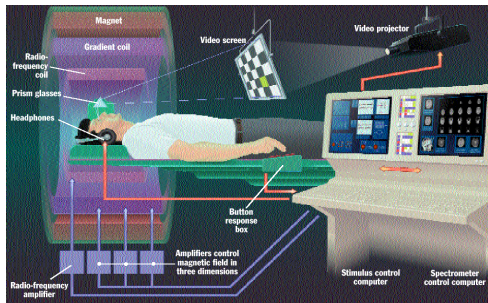
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## fMRI Setup



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[http://defiant.ssc.uwo.ca/Jody\\_web/fmri4dummies.htm](http://defiant.ssc.uwo.ca/Jody_web/fmri4dummies.htm)

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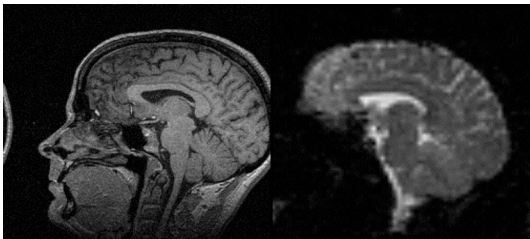
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## fMRI Acquisition

High spatial resolution

High temporal resolution



MP-RAGE

Voxel volume:  $1 \text{ mm}^3$

Imaging time: 6 min

EPI

Voxel volume:  $45 \text{ mm}^3$

Imaging time: 60 msec

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Buxton 2002

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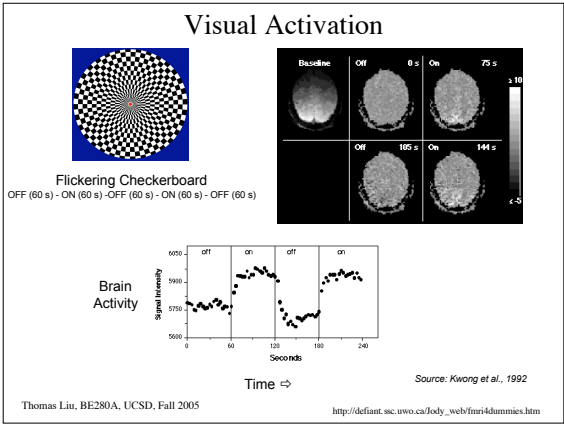
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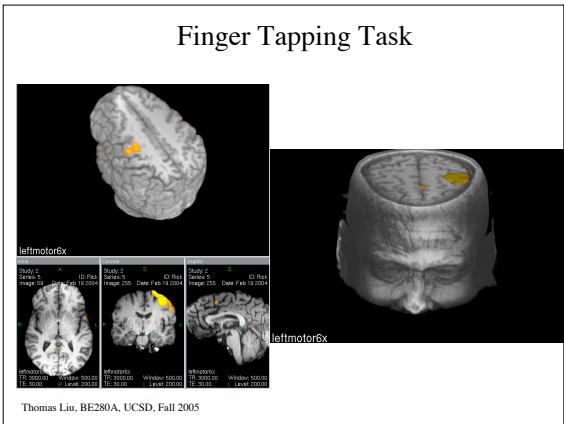
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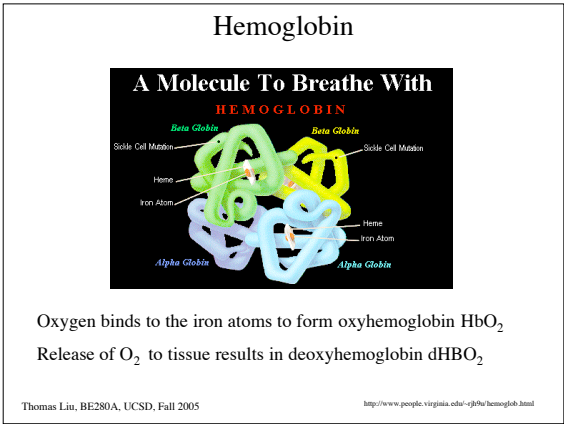
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## Effect of dHBO<sub>2</sub>

dHBO<sub>2</sub> is paramagnetic due to the iron atoms. As it becomes oxygenated, it becomes less paramagnetic.

dHBO<sub>2</sub> perturbs the local magnetic fields. As blood becomes more deoxygenated, the amount of perturbation increases and there is more dephasing of the spins. Thus as dHBO<sub>2</sub> increases we find that  $T_2^*$  decreases and the amplitude  $\exp(-TE/T_2^*)$  image of a  $T_2^*$  weighted image will decrease. Conversely as dHBO<sub>2</sub> decreases,  $T_2^*$  increases and we expect the signal amplitude to go up.

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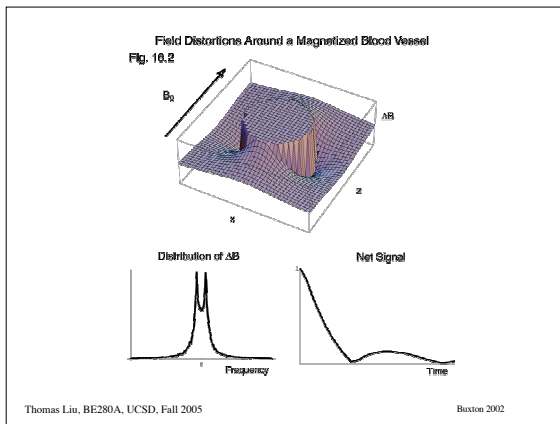
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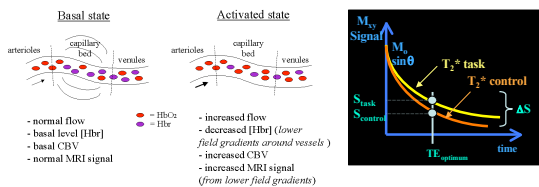
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## BOLD Effect

Blood Oxygen Level Dependent signal

neural activity  $\rightarrow$   $\uparrow$  blood flow  $\rightarrow$   $\uparrow$  oxyhemoglobin  $\rightarrow$   $\uparrow$   $T_2^*$   $\rightarrow$   $\uparrow$  MR signal



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[http://defiant.ssc.uwo.ca/Joely\\_web/fmr14dummies.htm](http://defiant.ssc.uwo.ca/Joely_web/fmr14dummies.htm)

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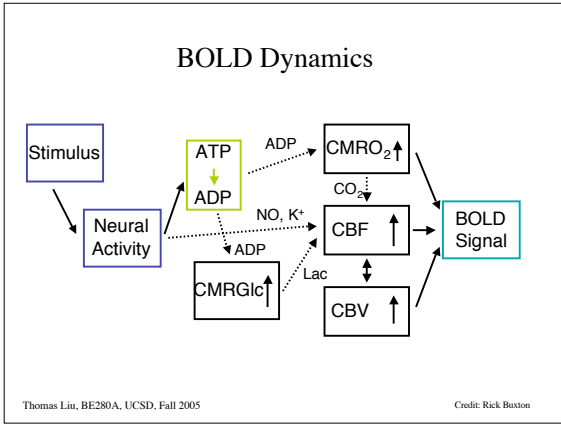
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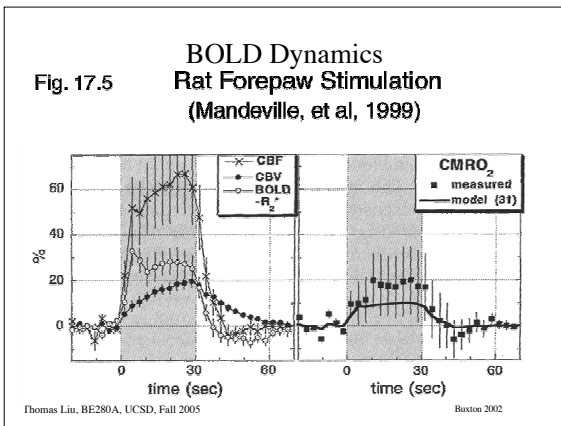
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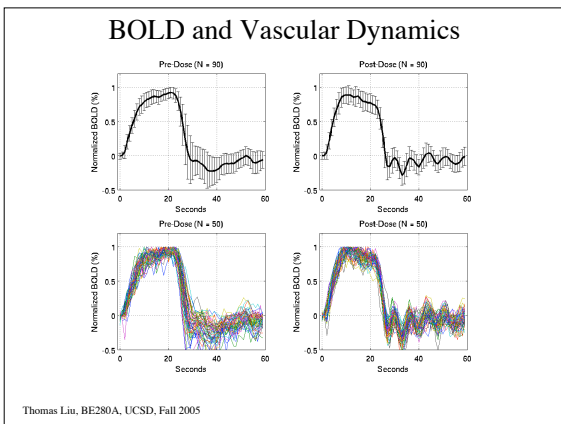
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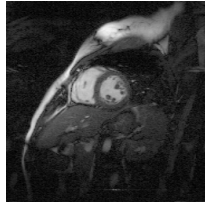
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## Cardiac Imaging



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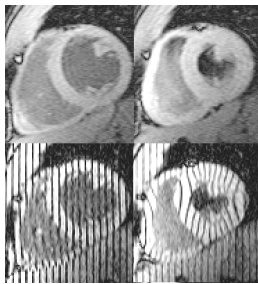
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## Cardiac Tagging



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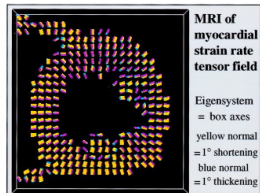
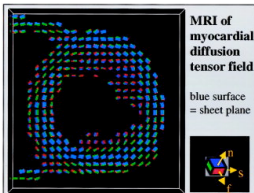
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## Cardiac Diffusion and Strain



Dou et al, MRM 2003

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