

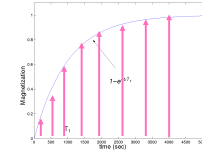
Bioengineering 280A
Principles of Biomedical Imaging

Fall Quarter 2014
MRI Lecture 5

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Longitudinal Relaxation

$$\frac{dM_z}{dt} = -\frac{M_z - M_0}{T_1}$$



After a 90 degree pulse $M_z(t) = M_0(1 - e^{-t/T_1})$

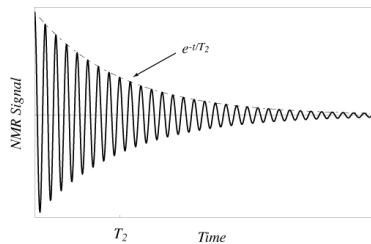
Due to exchange of energy between nuclei and the lattice (thermal vibrations). Process continues until thermal equilibrium as determined by Boltzmann statistics is obtained.

The energy ΔE required for transitions between down to up spins, increases with field strength, so that T_1 increases with \mathbf{B} .

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T2 Relaxation

Free Induction Decay (FID)



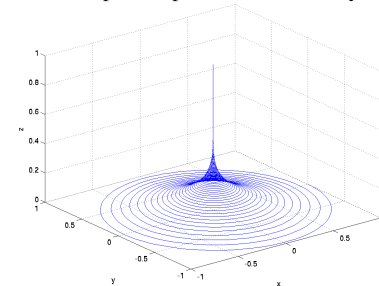
After a 90 degree
excitation

$$M_{xy}(t) = M_0 e^{-t/T_2}$$

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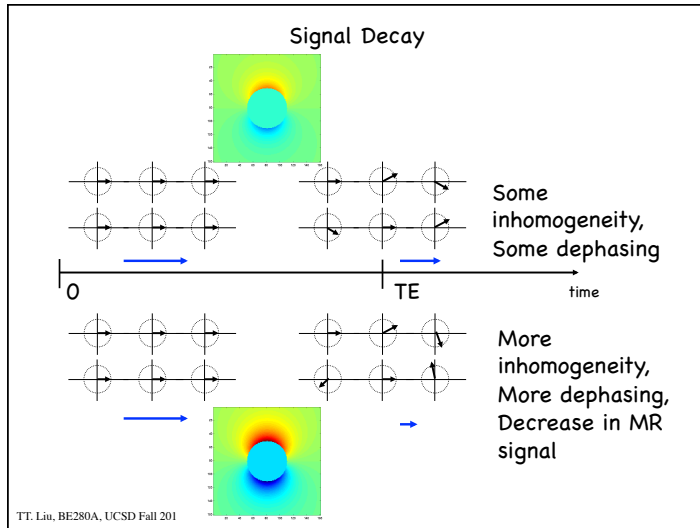
Summary

- 1) Longitudinal component recovers exponentially.
- 2) Transverse component precesses and decays exponentially.



Fact: Can show that $T_2 < T_1$ in order for $|M(t)| \leq M_0$
Physically, the mechanisms that give rise to T_1 relaxation
also contribute to transverse T_2 relaxation.

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T_2^* decay

The overall decay has the form.

$$\exp(-t/T_2^*(\vec{r}))$$

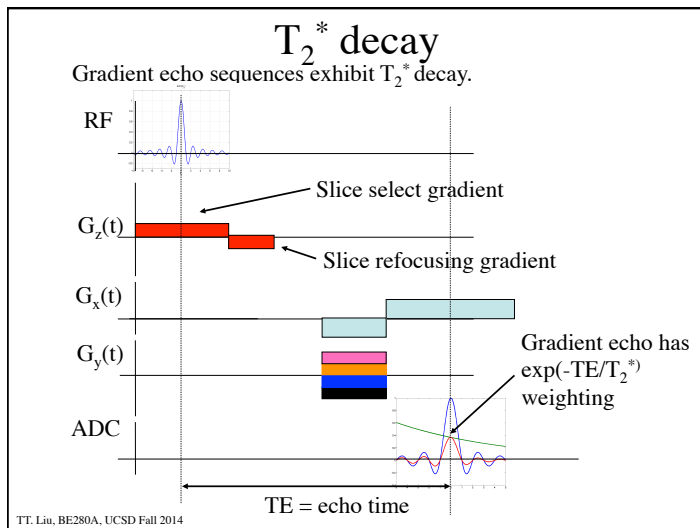
where

$$\frac{1}{T_2^*} = \frac{1}{T_2} + \frac{1}{T_2'}$$

Due to random motions of spins. Not reversible.

Due to static inhomogeneities. Reversible with a spin-echo sequence.

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Spin Echo

Discovered by Erwin Hahn in 1950.

The spin-echo can refocus the dephasing of spins due to static inhomogeneities. However, there will still be T_2 dephasing due to random motion of spins.

There is nothing that nuclear spins will not do for you, as long as you treat them as human beings. Erwin Hahn

Image: Larry Frank

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Spin Echo

Source: <http://mrsrl.stanford.edu/~brian/mri-movies/>

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Spin Echo

Phase at time τ

$$\varphi(\tau) = \int_0^\tau -\omega_E(\vec{r}) dt = -\omega_E(\vec{r})\tau$$

Phase after 180 pulse

$$\varphi(\tau^+) = \omega_E(\vec{r})\tau$$

Phase at time 2τ

$$\varphi(2\tau) = -\omega_E(\vec{r})\tau + \omega_E(\vec{r})\tau = 0$$

Image: Larry Frank

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Spin Echo Pulse Sequence

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Spin-echo Image

Gradient-Echo Image

<http://chickscope.beckman.uiuc.edu/roosts/carartifacts.html>

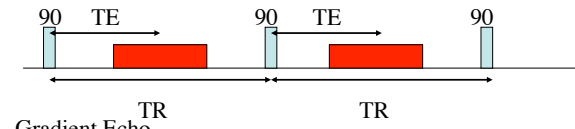
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Image Contrast

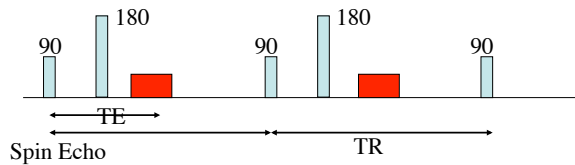
Different tissues exhibit different relaxation rates, T_1 , T_2 , and T_2^* . In addition different tissues can have different densities of protons. By adjusting the pulse sequence, we can create contrast between the tissues. The most basic way of creating contrast is adjusting the two sequence parameters: TE (echo time) and TR (repetition time).

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Saturation Recovery Sequence



$$I(x, y) = \rho(x, y) \left[1 - e^{-TR/T_1(x, y)} \right] e^{-TE/T_2^*(x, y)}$$



$$I(x, y) = \rho(x, y) \left[1 - e^{-TR/T_1(x, y)} \right] e^{-TE/T_2(x, y)}$$

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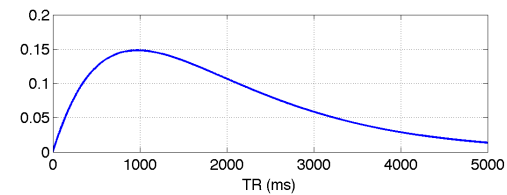
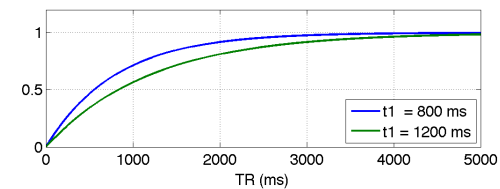
T1-Weighted Scans

Make TE very short compared to either T_2 or T_2^* . The resultant image has both proton and T_1 weighting.

$$I(x, y) \approx \rho(x, y) \left[1 - e^{-TR/T_1(x, y)} \right]$$

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T1-Weighted Scans



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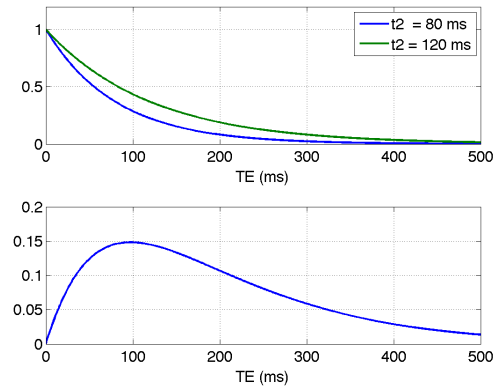
T2-Weighted Scans

Make TR very long compared to T_1 and use a spin-echo pulse sequence. The resultant image has both proton and T_2 weighting.

$$I(x, y) \approx \rho(x, y)e^{-TE/T_2}$$

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T2-Weighted Scans



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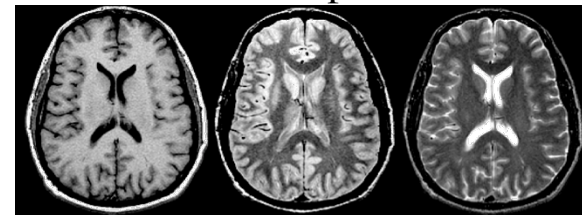
Proton Density Weighted Scans

Make TR very long compared to T_1 and use a very short TE. The resultant image is proton density weighted.

$$I(x, y) \approx \rho(x, y)$$

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Example



T_1 -weighted

Density-weighted

T_2 -weighted

Tissue	Proton Density	T1 (ms)	T2 (ms)
Csf	1.0	4000	2000
Gray	0.85	1350	110
White	0.7	850	80

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(a) Four images, all obtained with a common TR=5 seconds and TE=90, 50, 20, 15 ms (shown in reading order).

(b) Six images obtained with a common TE=15 ms and TR=500, 1000, 2000, 3000, 4000, 5000 ms (shown in reading order).

Figure 8: Phantom data which illustrates signal intensity and contrast for bottles filled with jello of varying consistency. Where is T_1 long/short? How long, how short? The same for T_2 ? Which bottles might be pure water? Which jello is most firm? What pictures are the most T_1 -, T_2 - and PD-weighted? Hanson 2009

- Which has the longest T1?
- Which has the shortest T1?
- Which has the longest T2?
- Which has the shortest T2?
- Which might be pure water?
- Which has the most firm jello?

1 2
3 4

PollEv.com/be280a

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(a) Four images, all obtained with a common TR=5 seconds and TE=90, 50, 20, 15 ms (shown in reading order).

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- Which is the most T1 weighted?
- Which is the most T2 weighted?
- Which is the most PD weighted?

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FLASH sequence

Gradient Echo

$$I(x,y) = \rho(x,y) \left[\frac{1 - e^{-TR/T_1(x,y)}}{1 - e^{-TR/T_1(x,y)} \cos \theta} \right] \sin \theta \exp(-TE/T_2^*)$$

Signal intensity is maximized at the Ernst Angle

$$\theta_E = \cos^{-1}(\exp(-TR/T_1))$$

FLASH equation assumes no coherence from shot to shot. In practice this is achieved with RF spoiling.

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FLASH sequence

Flash signal intensity; $T_1 = 1000$ ms

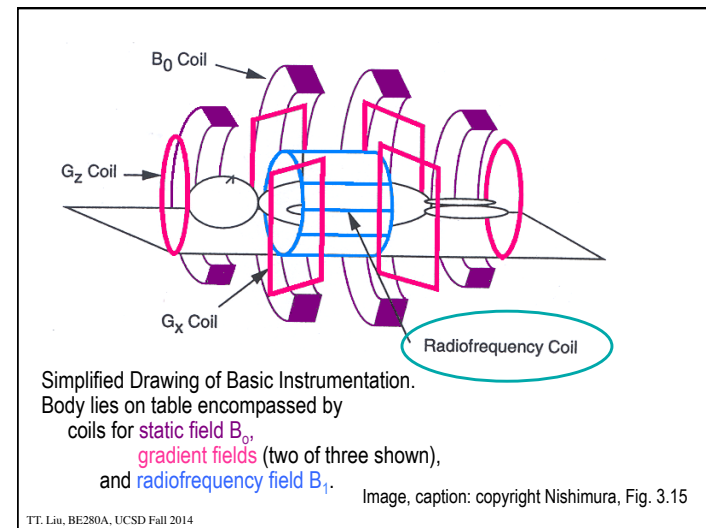
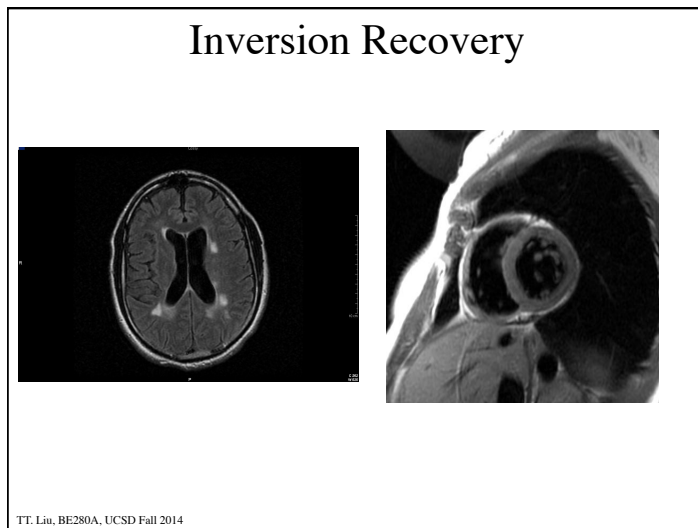
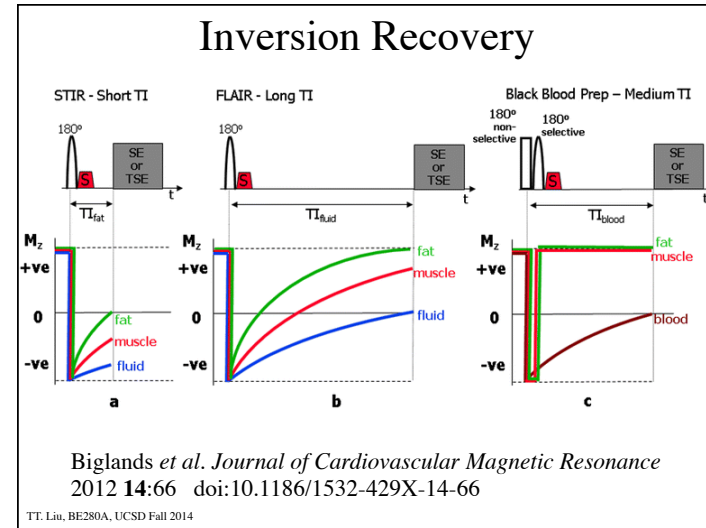
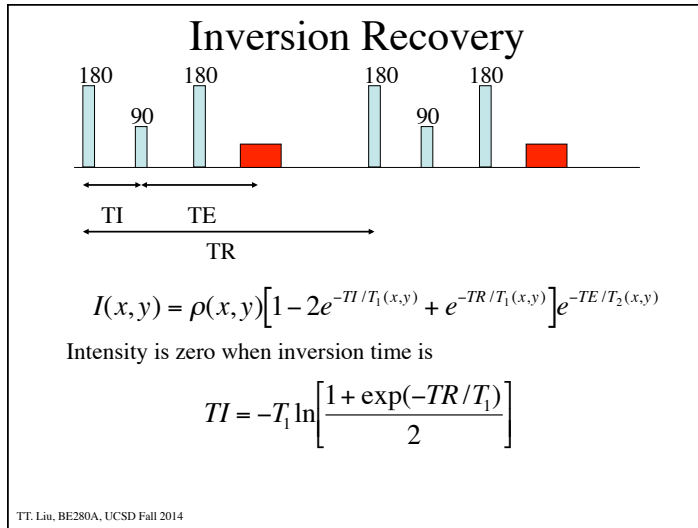
Signal Intensity

Flip Angle

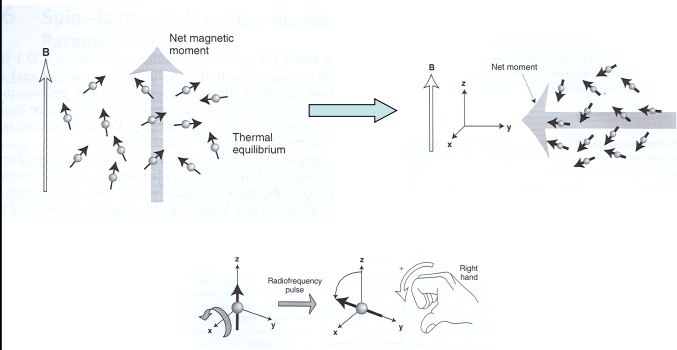
— TR = 30 ms
— TR = 100 ms
— TR = 500 ms

$$\theta_E = \cos^{-1}(\exp(-TR/T_1))$$

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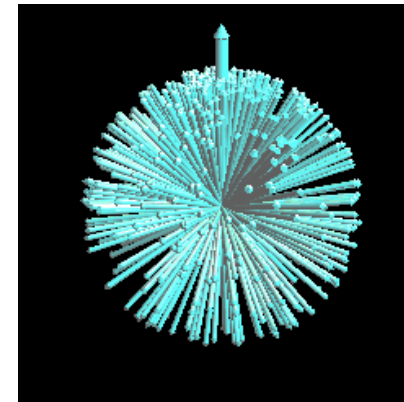
RF Excitation



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From Levitt, Spin Dynamics, 2001

RF Excitation



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<http://www.drcmr.dk/main/content/view/213/74/>

RF Excitation

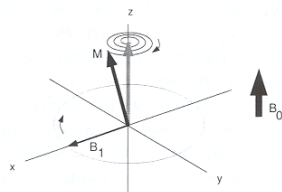


Image & caption: Nishimura, Fig. 3.2

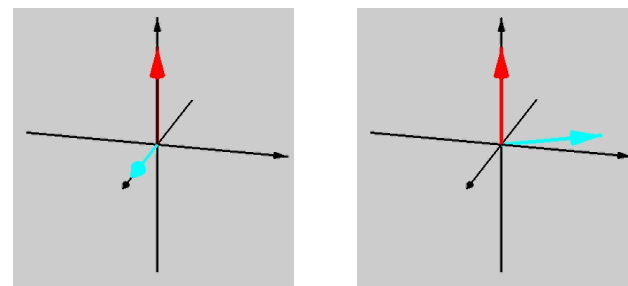
At equilibrium, net magnetization is parallel to the main magnetic field. How do we tip the magnetization away from equilibrium?

B_1 radiofrequency field tuned to Larmor frequency and applied in transverse (xy) plane induces nutation (at Larmor frequency) of magnetization vector as it tips away from the z -axis.
- lab frame of reference

<http://www.eecs.umich.edu/~7EdnoIHBME516/>

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RF Excitation



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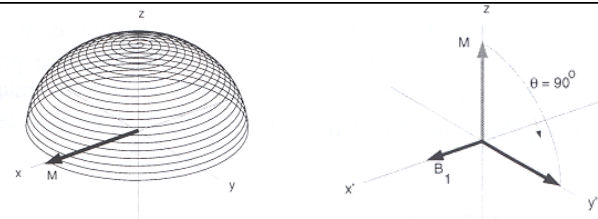
<http://www.eecs.umich.edu/~7EdnoIHBME516/>

Rotating Frame of Reference

Reference everything to the magnetic field at isocenter.

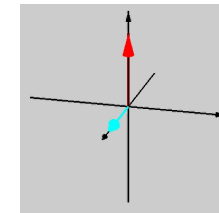


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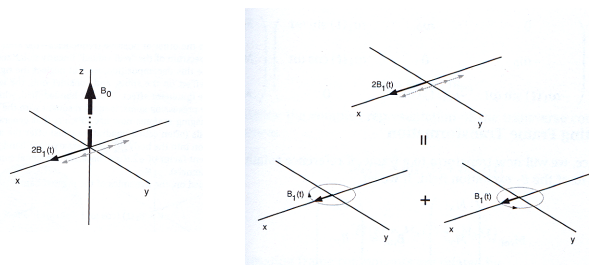
a) Laboratory frame behavior of **M**
Images & caption: Nishimura, Fig. 3.3

b) Rotating frame behavior of **M**



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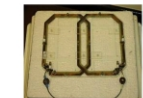
<http://www.eecs.umich.edu/%7Edno/BME516/>



$$\begin{aligned} \mathbf{B}_1(t) &= 2B_1(t)\cos(\omega t)\mathbf{i} \\ &= B_1(t)(\cos(\omega t)\mathbf{i} - \sin(\omega t)\mathbf{j}) + B_1(t)(\cos(\omega t)\mathbf{i} + \sin(\omega t)\mathbf{j}) \end{aligned}$$

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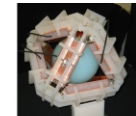
Nishimura 1996



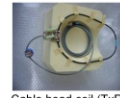
2-channel phased array for cardio MRI (Rx)



Breast coil with detached coupling box



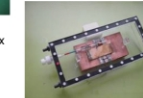
Octahedral head coil with 12 TxRx channels



Cable head coil (TxRx) for 129Xe (34.66 MHz)



"X coil", 125 MHz (Rx)



Tunable CSA hyperthermia module (97 MHz, Tx)



4-channel CSA array (TxRx)



125-MHz CSA



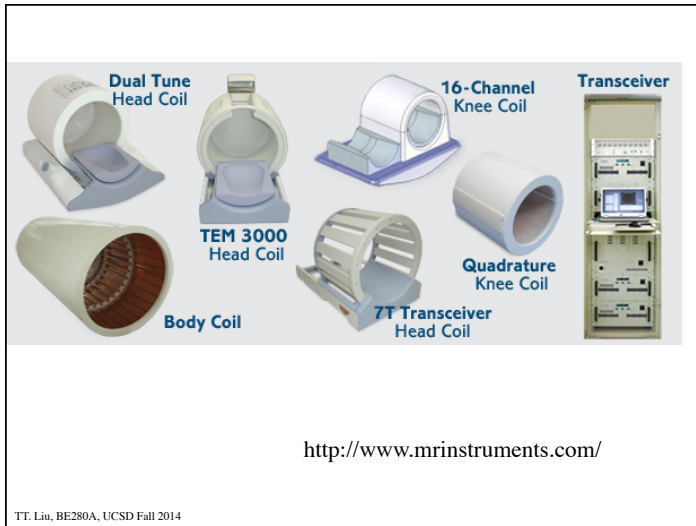
Lung coil (TxRx) with differential transmitter for 129Xe (34.66 MHz)



2-channel strip-line array (TxRx)

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<http://www.berlin.ptb.de/en/org/8/81/811/ResearchTopics/CoilDevelopment.html>



Precession

Analogous to motion of a gyroscope
Precesses at an angular frequency of

$$\omega = \gamma B$$

This is known as the **Larmor** frequency.

Movement of a Gyroscope
without
External Forces

Concept:
Hermann Hartel

Computer Graphics:
Jan Paul

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http://www.astrophysik.uni-kiel.de/~hhaertelmpg_e/gyros_free.mpg

Rotating Frame Bloch Equation

$$\frac{d\mathbf{M}_{rot}}{dt} = \mathbf{M}_{rot} \times \gamma \mathbf{B}_{eff}$$

$$\mathbf{B}_{eff} = \mathbf{B}_{rot} + \frac{\omega_{rot}}{\gamma} \mathbf{k}; \quad \omega_{rot} = \begin{bmatrix} 0 \\ 0 \\ -\omega \end{bmatrix}$$

Note: we use the RF frequency to define the rotating frame. If this RF frequency is on-resonance, then the main B0 field doesn't cause any precession in the rotating frame. However, if the RF frequency is off-resonance, then there will be a net precession in the rotating frame that is give by the difference between the RF frequency and the local Larmor frequency.

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Let $\mathbf{B}_{rot} = B_1(t)\mathbf{i} + B_0\mathbf{k}$

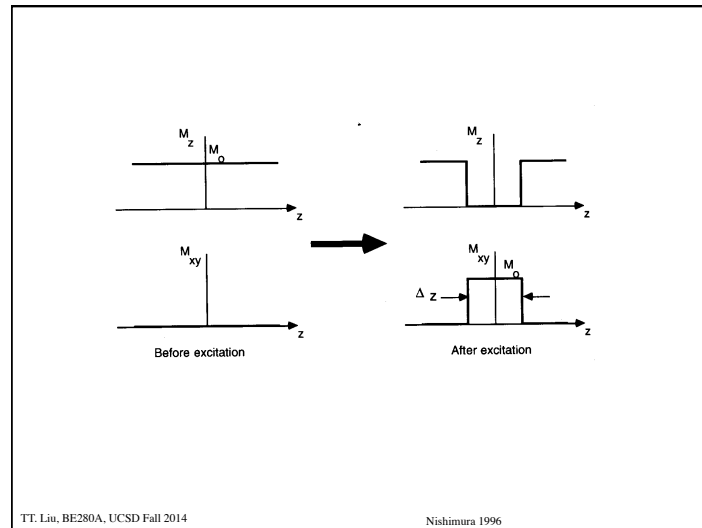
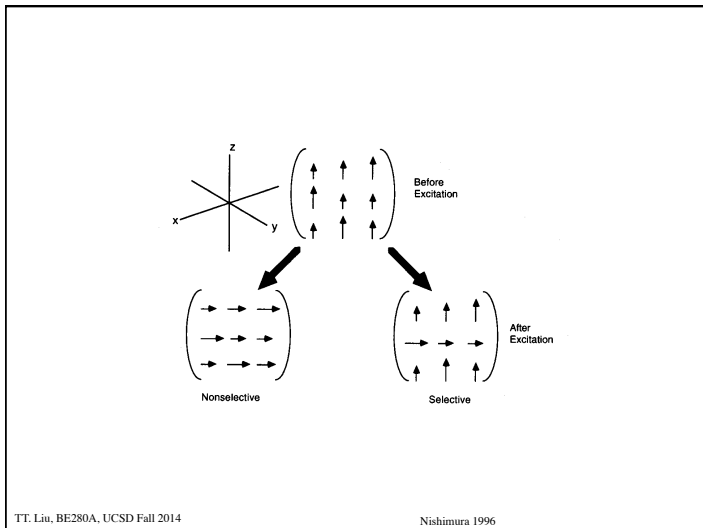
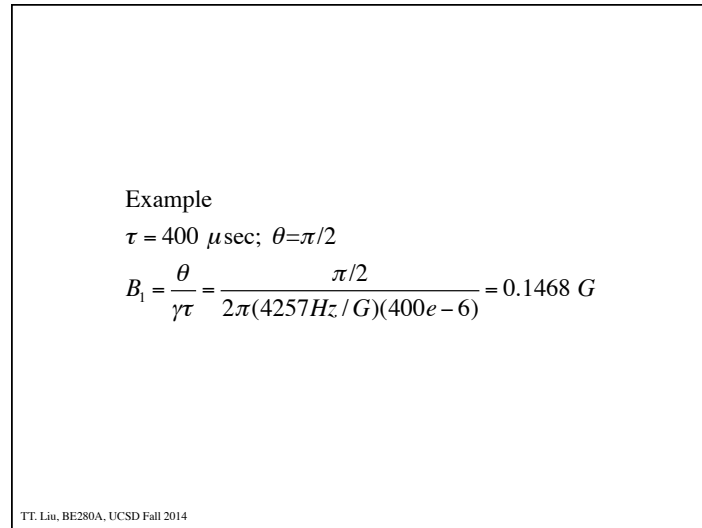
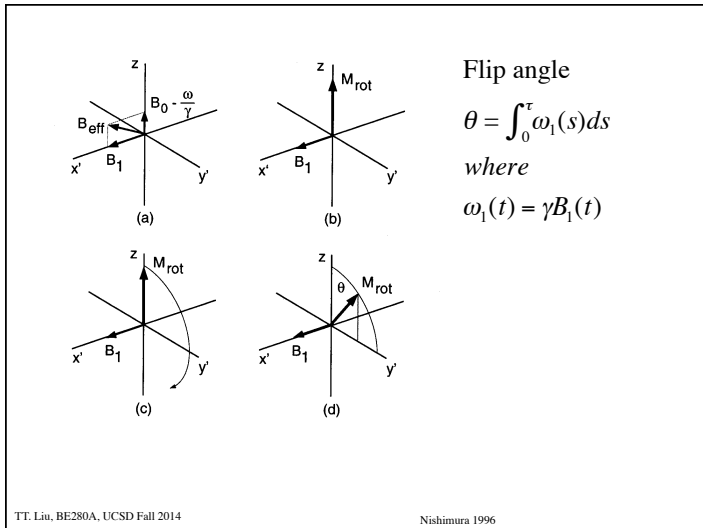
$$\mathbf{B}_{eff} = \mathbf{B}_{rot} + \frac{\omega_{rot}}{\gamma} \mathbf{k}$$

$$= B_1(t)\mathbf{i} + \left(B_0 - \frac{\omega}{\gamma} \right) \mathbf{k}$$

If $\omega = \omega_0$
 $= \gamma B_0$

Then $\mathbf{B}_{eff} = B_1(t)\mathbf{i}$

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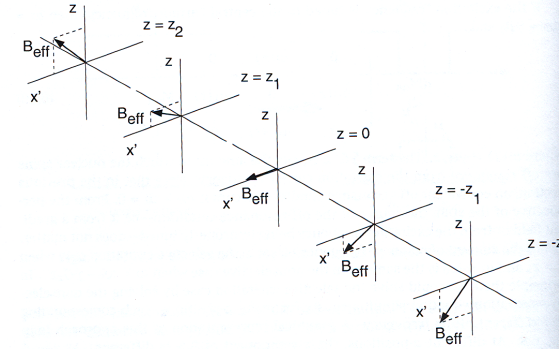
Let $\mathbf{B}_{rot} = B_1(t)\mathbf{i} + (B_0 + \gamma G_z z)\mathbf{k}$

$$\begin{aligned} \mathbf{B}_{eff} &= \mathbf{B}_{rot} + \frac{\omega_{rot}}{\gamma} \\ &= B_1(t)\mathbf{i} + \left(B_0 + \gamma G_z z - \frac{\omega}{\gamma} \right) \mathbf{k} \end{aligned}$$

If $\omega = \omega_0$

$$\mathbf{B}_{eff} = B_1(t)\mathbf{i} + (\gamma G_z z)\mathbf{k}$$

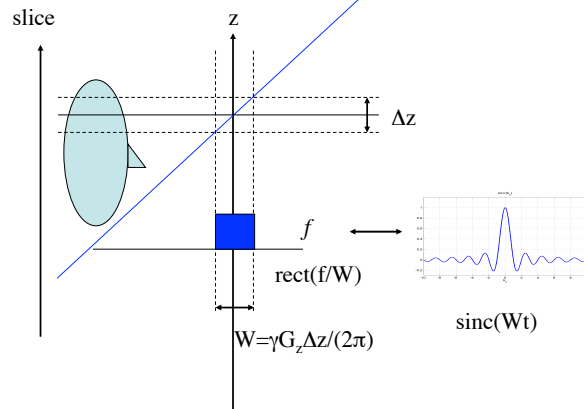
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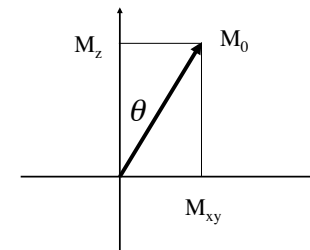
Nishimura 1996

Slice Selection



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Small Tip Angle Approximation

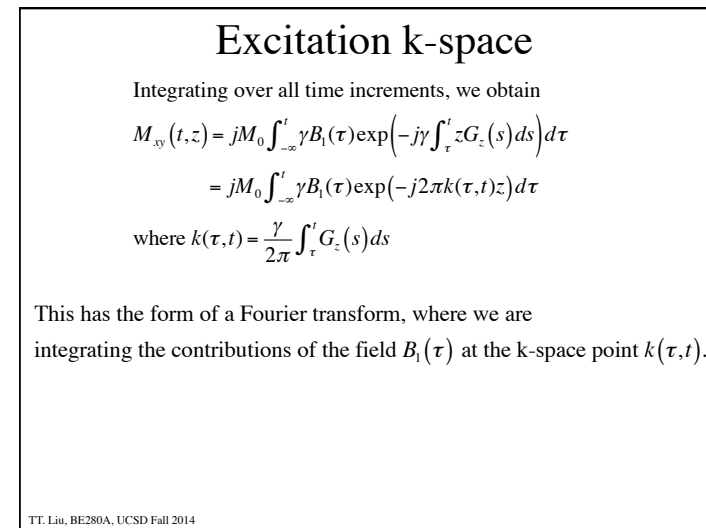
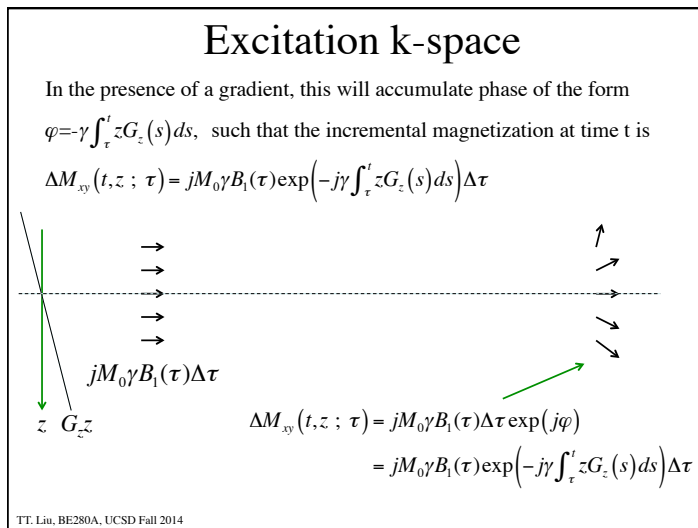
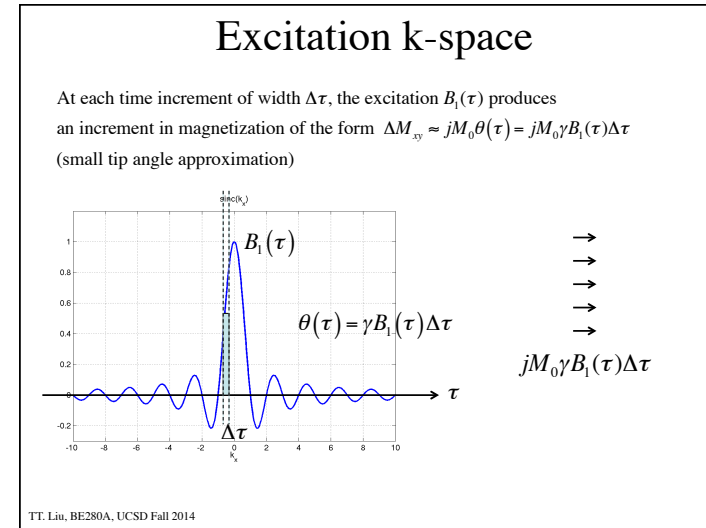
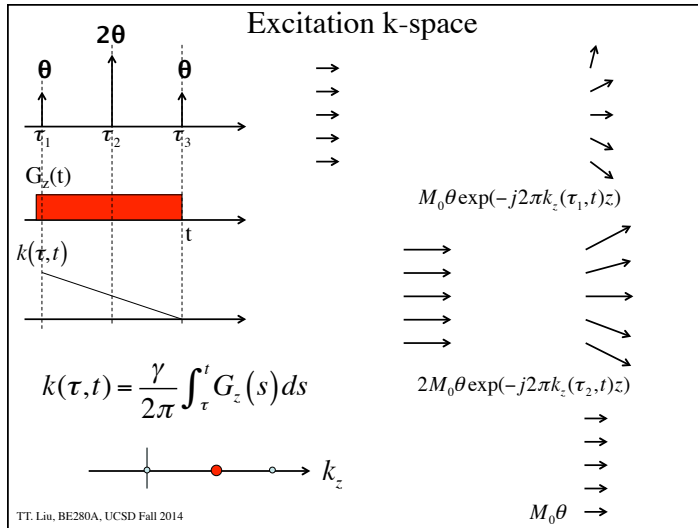


For small θ

$$M_z = M_0 \cos \theta \approx M_0$$

$$M_{xy} = M_0 \sin \theta \approx M_0 \theta$$

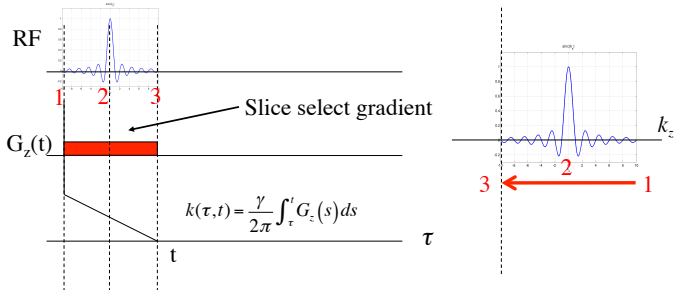
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Excitation k-space

$$M_{xy}(t, z) = jM_0 \int_{-\infty}^t \gamma B_1(\tau) \exp(-j2\pi k(\tau, t)z) d\tau$$

This has the form of a Fourier transform, where we are integrating the contributions of the field $B_1(\tau)$ at the k-space point $k(\tau, t)$.

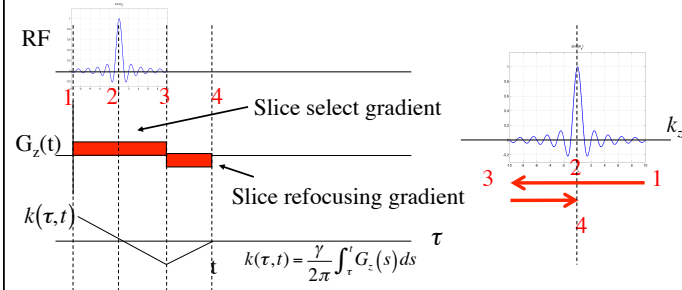


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Refocusing

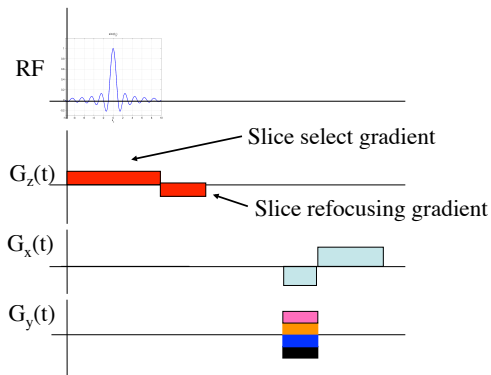
$$M_{xy}(t, z) = jM_0 \int_{-\infty}^t \gamma B_1(\tau) \exp(-j2\pi k(\tau, t)z) d\tau$$

This has the form of a Fourier transform, where we are integrating the contributions of the field $B_1(\tau)$ at the k-space point $k(\tau, t)$.



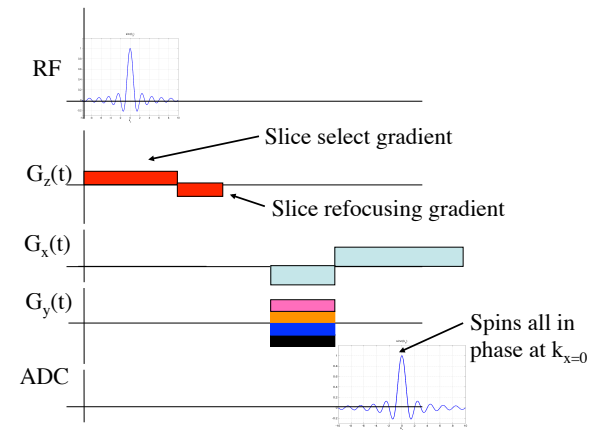
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Slice Selection



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Gradient Echo



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