

Bioengineering 280A
Principles of Biomedical Imaging

Fall Quarter 2015
CT/Fourier Lecture 2

TT Liu, BE280A, UCSD Fall 2015

In-class Exercise

$$\mu(x, y) = \text{rect}(x, y/2)$$

Sketch this object.
What are the projections at theta = 0 and 90 degrees?
For what angle is the projection maximized?

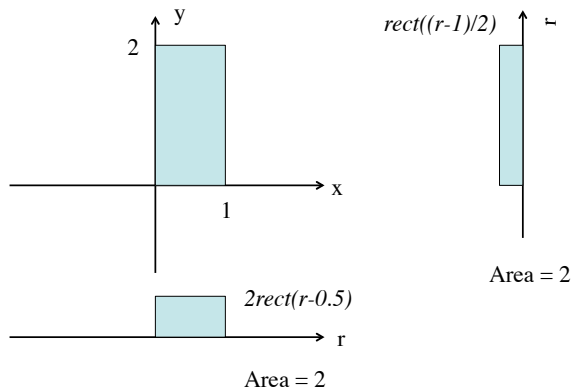
PollEv.com/be280a

TT Liu, BE280A, UCSD Fall 2015

Example

$$\mu(x, y) = \text{rect}(x - 0.5, (y - 1)/2)$$

Sketch this object.
What are the projections at theta = 0 and 90 degrees?
For what angle is the projection maximized?

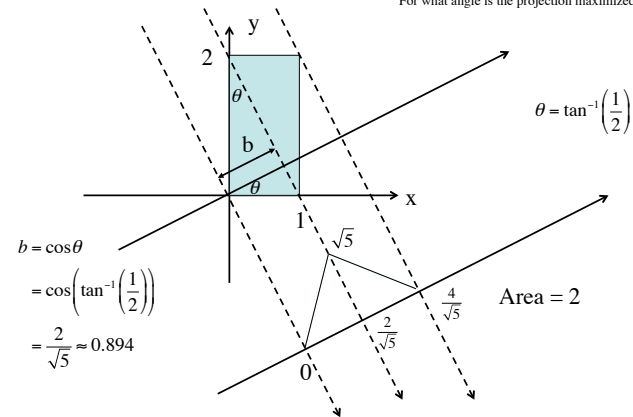


TT Liu, BE280A, UCSD Fall 2015

Example

$$\mu(x, y) = \text{rect}(x - 0.5, (y - 1)/2)$$

Sketch this object.
What are the projections at theta = 0 and 90 degrees?
For what angle is the projection maximized?



TT Liu, BE280A, UCSD Fall 2015

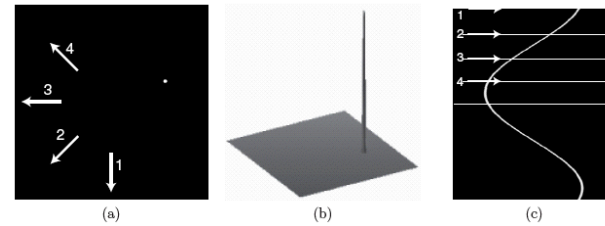
Example

$$f(x,y) = \begin{cases} 1 & x^2 + y^2 \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{aligned} g(l,\theta=0) &= \int_{-\infty}^{\infty} f(l,y) dy \\ &= \int_{-\sqrt{1-l^2}}^{\sqrt{1-l^2}} dy \\ &= \begin{cases} 2\sqrt{1-l^2} & |l| \leq 1 \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

TT Liu, BE280A, UCSD Fall 2015

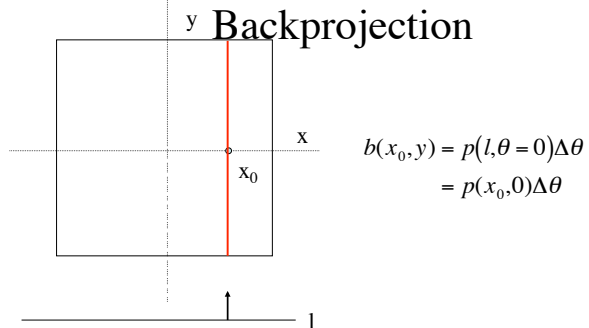
Sinogram



TT Liu, BE280A, UCSD Fall 2015

Suetens 2002

Backprojection



$$\begin{aligned} b(x_0,y) &= p(l,\theta=0)\Delta\theta \\ &= p(x_0,0)\Delta\theta \end{aligned}$$

$$b_\theta(x,y) = g(x \cos \theta + y \sin \theta) \Delta\theta$$

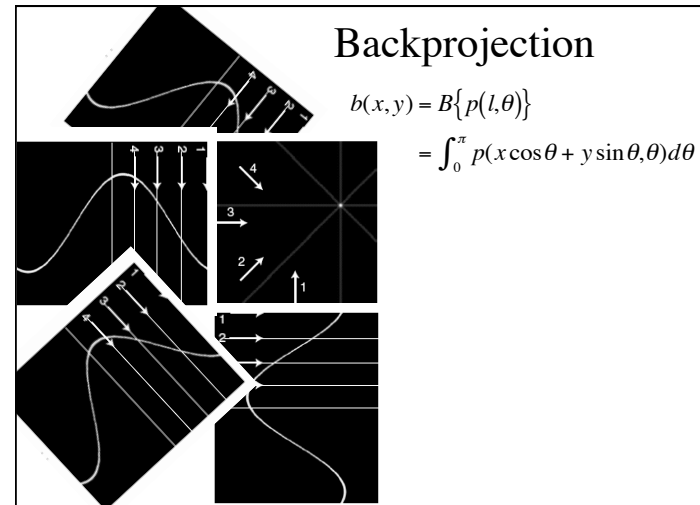
$$b(x,y) = B\{g(l,\theta)\}$$

$$= \int_0^\pi g(x \cos \theta + y \sin \theta) d\theta$$

TT Liu, BE280A, UCSD Fall 2015

Suetens 2002

Backprojection



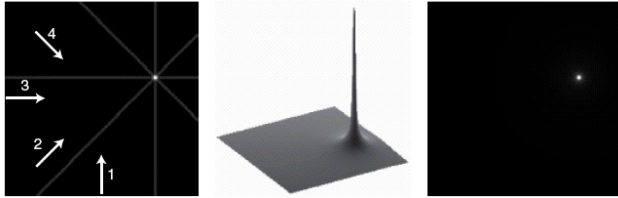
$$b(x,y) = B\{p(l,\theta)\}$$

$$= \int_0^\pi p(x \cos \theta + y \sin \theta) d\theta$$

TT Liu, BE280A, UCSD Fall 2015

Suetens 2002

Backprojection



$$b(x, y) = B\{p(l, \theta)\} = \int_0^\pi p(x \cos \theta + y \sin \theta, \theta) d\theta$$

TT Liu, BE280A, UCSD Fall 2015

Suetens 2002

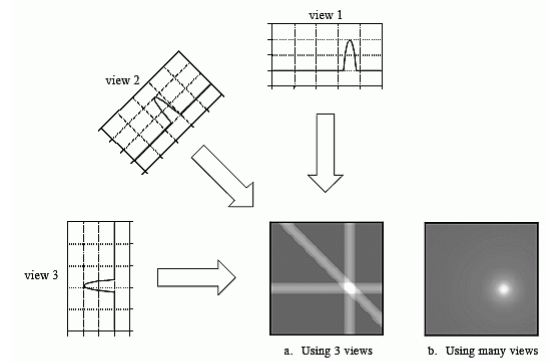


FIGURE 25-16 Backprojection. Backprojection reconstructs an image by taking each view and *smearing* it along the path it was originally acquired. The resulting image is a blurry version of the correct image.

<http://www.dspguide.com/ch25/5.htm>

TT Liu, BE280A, UCSD Fall 2015

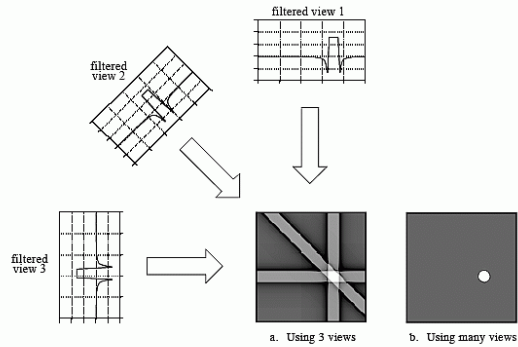
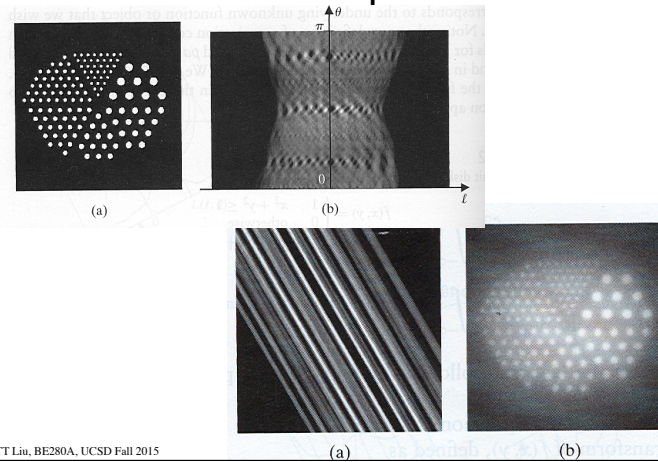


FIGURE 25-17 Filtered backprojection. Filtered backprojection reconstructs an image by filtering each view before backprojection. This removes the blurring seen in simple backprojection, and results in a mathematically exact reconstruction of the image. Filtered backprojection is the most commonly used algorithm for computed tomography systems.

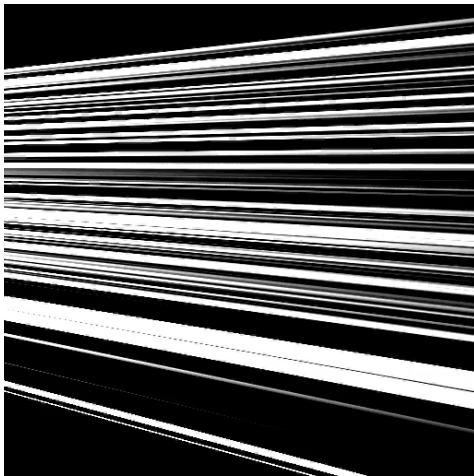
<http://www.dspguide.com/ch25/5.htm>

TT Liu, BE280A, UCSD Fall 2015

Example



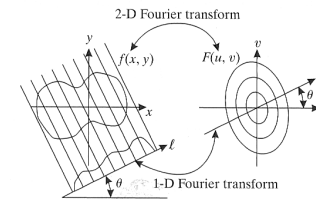
TT Liu, BE280A, UCSD Fall 2015



TT Liu, BE280A, UCSD Fall 2015

Projection Slice Theorem

$$\begin{aligned}
 G(\rho, \theta) &= \int_{-\infty}^{\infty} g(l, \theta) e^{-j2\pi \rho l} dl \\
 &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \delta(x \cos \theta + y \sin \theta - l) e^{-j2\pi \rho l} dx dy dl \\
 &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi \rho (x \cos \theta + y \sin \theta)} dx dy \\
 &= F_{2D}[f(x, y)]_{u = \rho \cos \theta, v = \rho \sin \theta}
 \end{aligned}$$

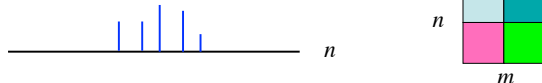


TT Liu, BE280A, UCSD Fall 2015

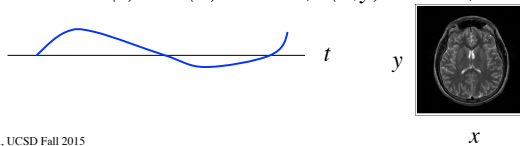
Prince&Links 2006

Signals and Images

Discrete-time/space signal / image: continuous valued function with a discrete time/space index, denoted as $s[n]$ for 1D, $s[m, n]$ for 2D, etc.



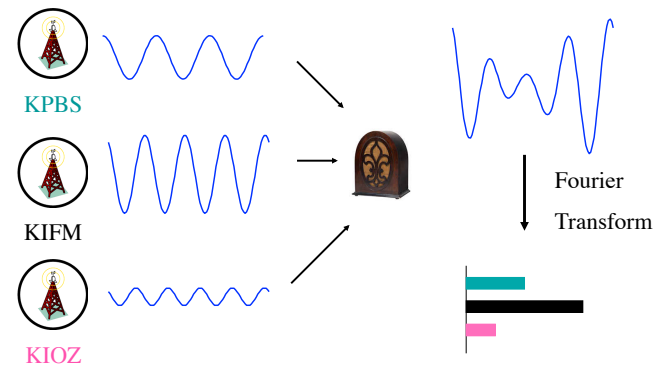
Continuous-time/space signal / image: continuous valued function with a continuous time/space index, denoted as $s(t)$ or $s(x)$ for 1D, $s(x, y)$ for 2D, etc.



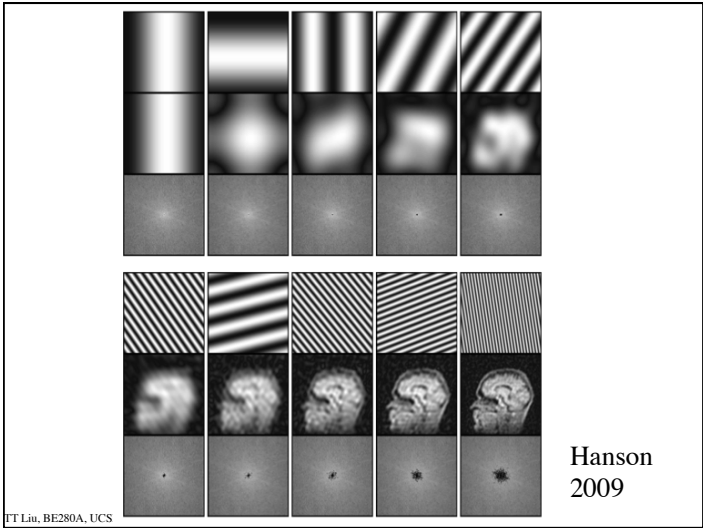
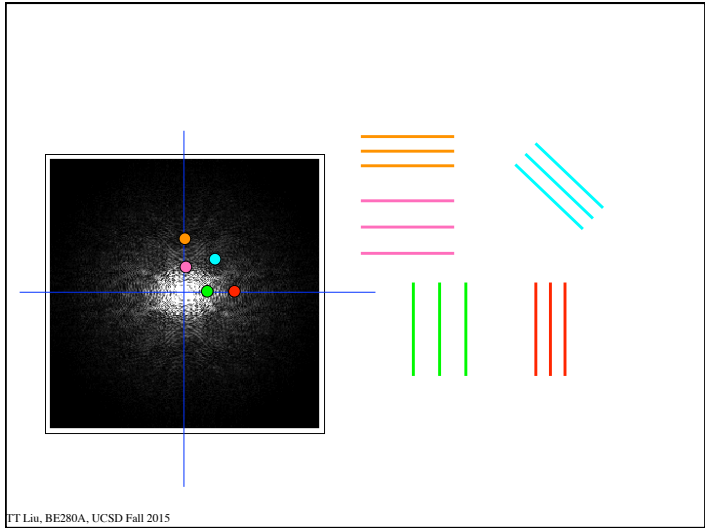
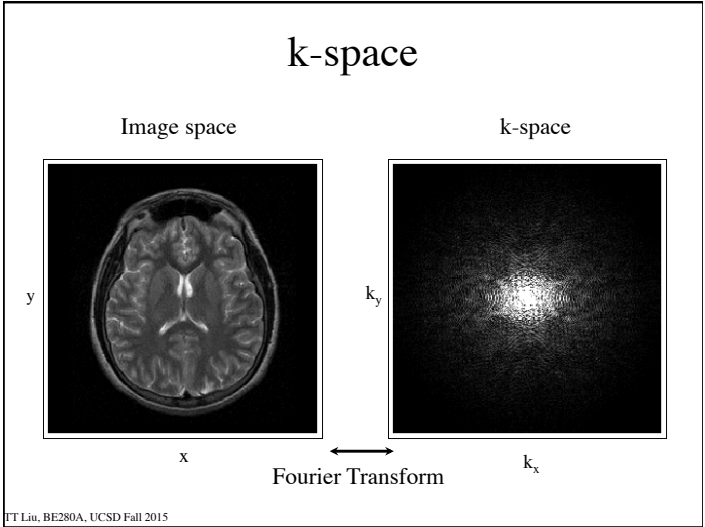
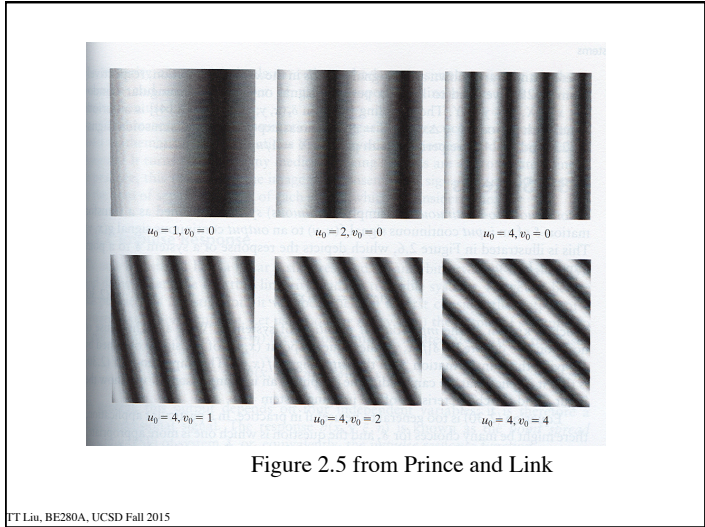
TT Liu, BE280A, UCSD Fall 2015

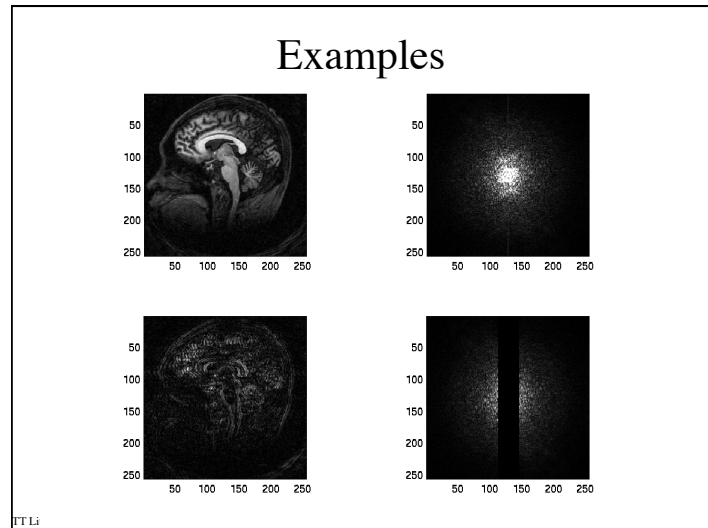
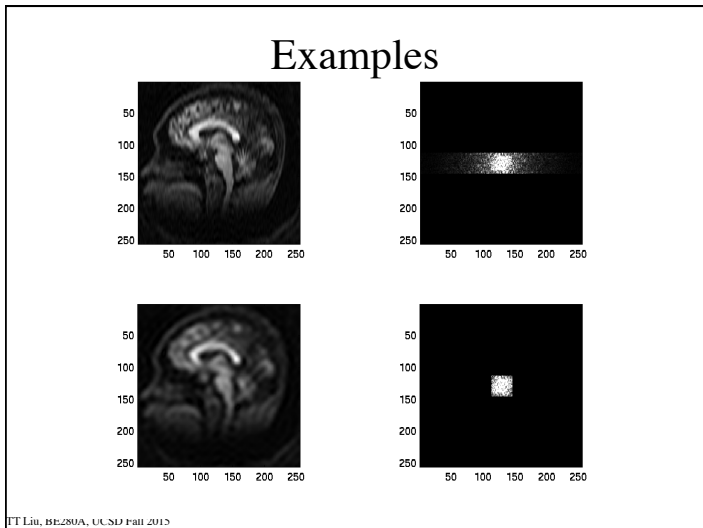
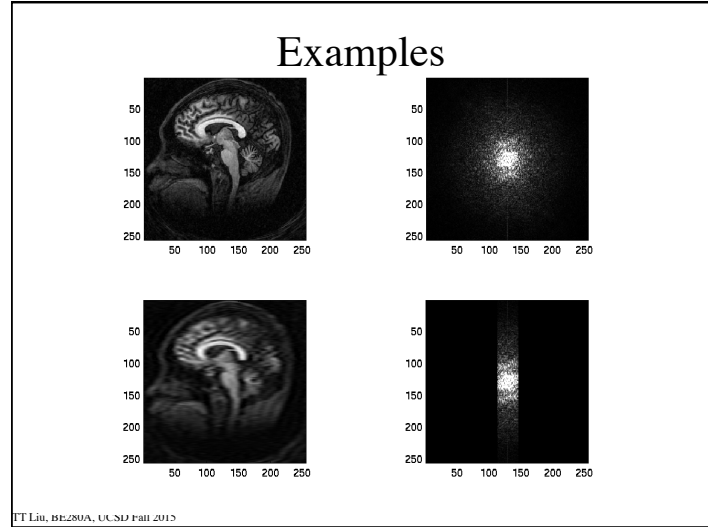
x

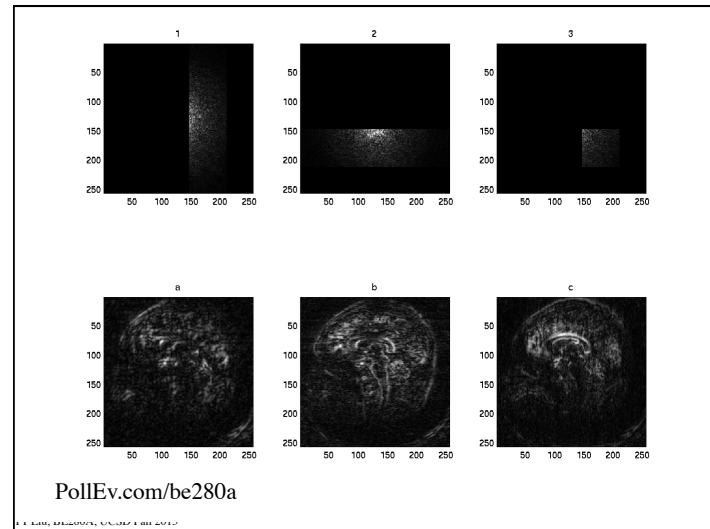
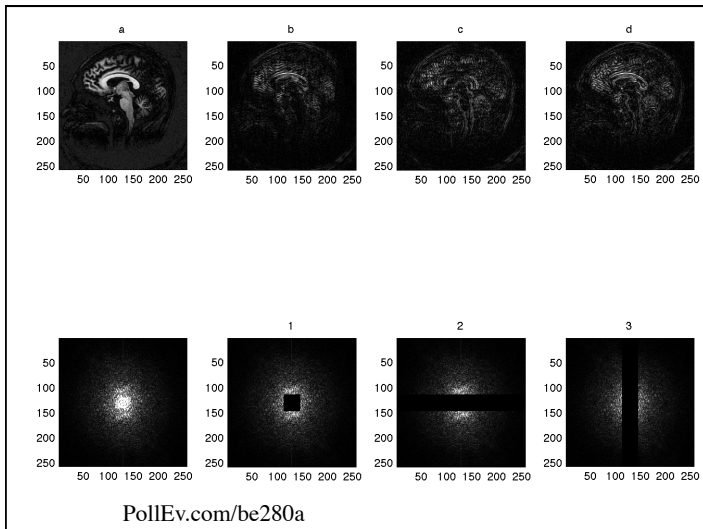
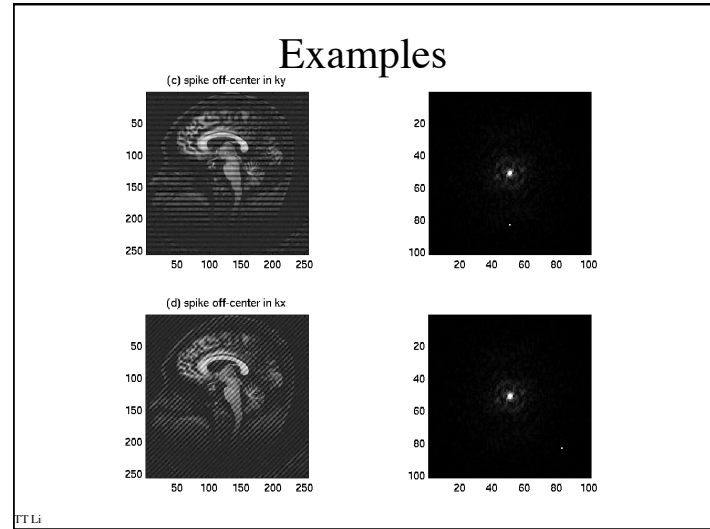
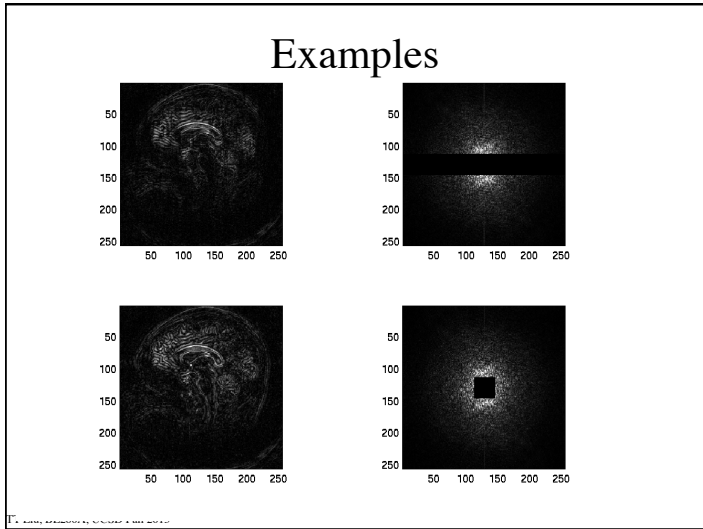
1D Fourier Transform

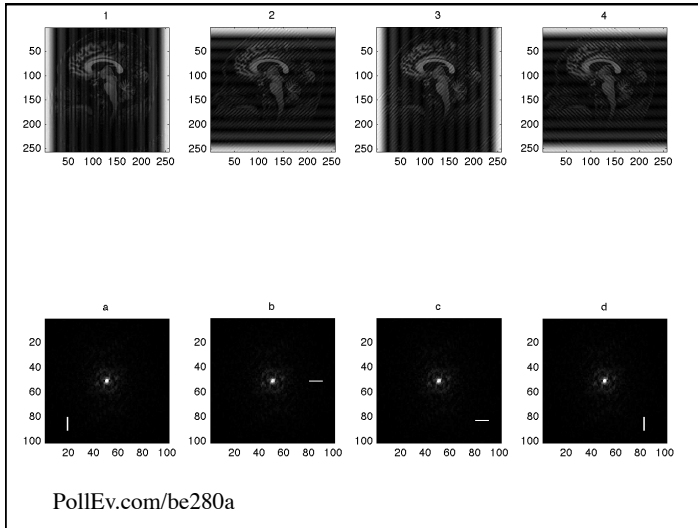


TT Liu, BE280A, UCSD Fall 2015









The Fourier Transform

Fourier Transform (FT)

$$G(f) = \int_{-\infty}^{\infty} g(t)e^{-j2\pi ft} dt = F\{g(t)\}$$

Inverse Fourier Transform

$$g(t) = \int_{-\infty}^{\infty} G(f)e^{j2\pi ft} df = F^{-1}\{G(f)\}$$

TT Liu, BE280A, UCSD Fall 2015

Units

Temporal Coordinates, e.g. t in seconds, f in cycles/second

$$G(f) = \int_{-\infty}^{\infty} g(t)e^{-j2\pi ft} dt \quad \text{Fourier Transform}$$

$$g(t) = \int_{-\infty}^{\infty} G(f)e^{j2\pi ft} df \quad \text{Inverse Fourier Transform}$$

Spatial Coordinates, e.g. x in cm, k_x is spatial frequency in cycles/cm

$$G(k_x) = \int_{-\infty}^{\infty} g(x)e^{-j2\pi k_x x} dx \quad \text{Fourier Transform}$$

$$g(x) = \int_{-\infty}^{\infty} G(k_x)e^{j2\pi k_x x} dk_x \quad \text{Inverse Fourier Transform}$$

TT Liu, BE280A, UCSD Fall 2015

Complex Numbers

$$j = \sqrt{-1}$$

$$j^2 = ?$$

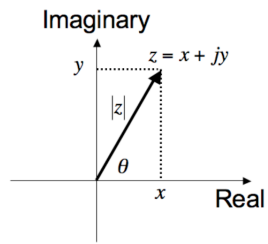
$$(3 + 2j)(3 - 2j) = ?$$

$$j^2 = -1$$

$$(3 + 2j)(3 - 2j) = 9 - 4j^2 = 13$$

TT Liu, BE280A, UCSD Fall 2015

Complex Numbers



$$z = 2 + 1j$$

$$|z| = \sqrt{2^2 + 1} = \sqrt{5}$$

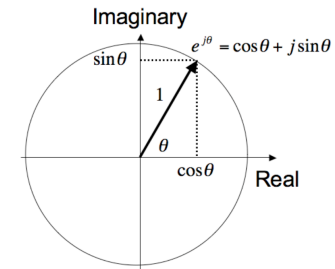
$$\theta = \tan^{-1}\left(\frac{1}{2}\right) = 26.6 \text{ degrees}$$

TT Liu, BE280A, UCSD Fall 2015

Euler's Formula

$$e^{j\theta} = \cos\theta + j\sin\theta$$

$$z = x + jy = |z|e^{j\theta}$$



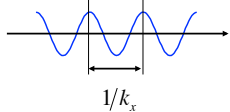
TT Liu, BE280A, UCSD Fall 2015

1D Fourier Transform

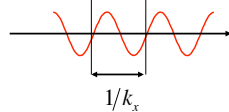
$$G(k_x) = \int_{-\infty}^{\infty} g(x) \exp(-j2\pi k_x x) dx$$

$$= \int_{-\infty}^{\infty} g(x) \cos(2\pi k_x x) dx - j \int_{-\infty}^{\infty} g(x) \sin(2\pi k_x x) dx$$

The part of $g(x)$ that "looks" like $\cos(2\pi k_x x)$



The part of $g(x)$ that "looks" like $\sin(2\pi k_x x)$



TT Liu, BE280A, UCSD Fall 2015

Computing Transforms

$$F(\delta(x)) = \int_{-\infty}^{\infty} \delta(x) e^{-j2\pi k_x x} dx = 1$$

$$F(\delta(x - x_0)) = \int_{-\infty}^{\infty} \delta(x - x_0) e^{-j2\pi k_x x} dx = e^{-j2\pi k_x x_0}$$

$$F(\Pi(x)) = \int_{-1/2}^{1/2} e^{-j2\pi k_x x} dx$$

$$= \frac{e^{-j\pi k_x} - e^{j\pi k_x}}{-j2\pi k_x}$$

$$= \frac{\sin(\pi k_x)}{\pi k_x} = \text{sinc}(k_x)$$

TT Liu, BE280A, UCSD Fall 2015

Computing Transforms

$$F(1) = \int_{-\infty}^{\infty} e^{-j2\pi k_x x} dx = ???$$

Define $h(k_x) = \int_{-\infty}^{\infty} e^{-j2\pi k_x x} dx$ and see what it does under an integral.

$$\begin{aligned} \int_{-\infty}^{\infty} G(k_x)h(k_x)dk_x &= \int_{-\infty}^{\infty} G(k_x) \int_{-\infty}^{\infty} e^{-j2\pi k_x x} dx dk_x \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} G(k_x) e^{-j2\pi k_x x} dk_x dx \\ &= \int_{-\infty}^{\infty} g(-x) dx \\ &= G(0) \end{aligned}$$

$$\text{Therefore, } F(1) = \int_{-\infty}^{\infty} e^{-j2\pi k_x x} dx = \delta(k_x)$$

TT Liu, BE280A, UCSD Fall 2015

Computing Transforms

Similarly,

$$F\{e^{j2\pi k_0 x}\} = \delta(k_x - k_0)$$

$$F\{\cos 2\pi k_0 x\} = \frac{1}{2}(\delta(k_x - k_0) + \delta(k_x + k_0))$$

$$F\{\sin 2\pi k_0 x\} = \frac{1}{2j}(\delta(k_x - k_0) - \delta(k_x + k_0))$$

TT Liu, BE280A, UCSD Fall 2015

Duality

Note the similarity between these two transforms

$$\begin{aligned} F\{e^{j2\pi ax}\} &= \delta(k_x - a) \\ F\{\delta(x - a)\} &= e^{-j2\pi ka} \end{aligned}$$

These are specific cases of duality

$$F\{G(x)\} = g(-k_x)$$

TT Liu, BE280A, UCSD Fall 2015

Application of Duality

$$F\{\text{sinc}(x)\} = \int_{-\infty}^{\infty} \frac{\sin \pi x}{\pi x} e^{-j2\pi k_x x} dx = ??$$

Recall that $F\{\Pi(x)\} = \text{sinc}(k_x)$.

Therefore from duality, $F\{\text{sinc}(x)\} = \Pi(-k_x) = \Pi(k_x)$

TT Liu, BE280A, UCSD Fall 2015

2D Fourier Transform

Fourier Transform

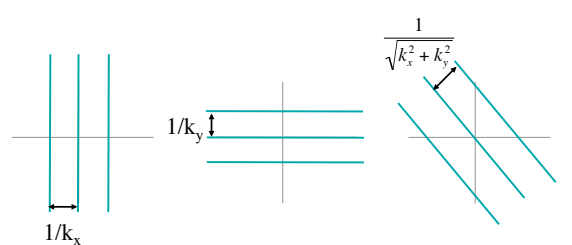
$$G(k_x, k_y) = F[g(x, y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) e^{-j2\pi(k_x x + k_y y)} dx dy$$

Inverse Fourier Transform

$$g(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} G(k_x, k_y) e^{j2\pi(k_x x + k_y y)} dk_x dk_y$$

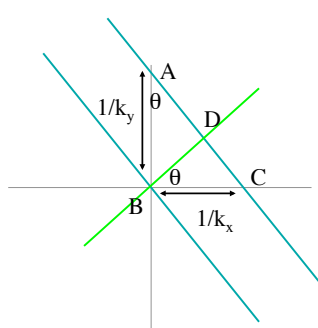
TT Liu, BE280A, UCSD Fall 2015

Plane Waves

$$e^{j2\pi(k_x x + k_y y)} = \cos(2\pi(k_x x + k_y y)) + j \sin(2\pi(k_x x + k_y y))$$


TT Liu, BE280A, UCSD Fall 2015

Plane Waves



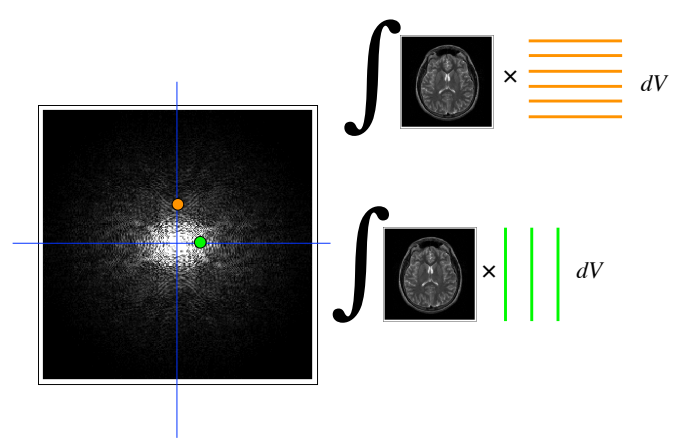
$$\Delta ABC \sim \Delta BDC$$

$$\frac{AC}{BC} = \frac{AB}{BD}$$

$$BD = AB \frac{BC}{AC} = \frac{\frac{1}{k_y} \frac{1}{k_x}}{\sqrt{\frac{1}{k_x^2} + \frac{1}{k_y^2}}} = \frac{1}{\sqrt{k_x^2 + k_y^2}}$$

$$\theta = \arctan\left(\frac{k_y}{k_x}\right)$$

TT Liu, BE280A, UCSD Fall 2015



TT Liu, BE280A, UCSD Fall 2015

Separable Functions

$g(x, y)$ is said to be a separable function if it can be written as $g(x, y) = g_x(x)g_y(y)$

The Fourier Transform is then separable as well.

$$\begin{aligned} G(k_x, k_y) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) e^{-j2\pi(k_x x + k_y y)} dx dy \\ &= \int_{-\infty}^{\infty} g_x(x) e^{-j2\pi k_x x} dx \int_{-\infty}^{\infty} g_y(y) e^{-j2\pi k_y y} dy \\ &= G_x(k_x) G_y(k_y) \end{aligned}$$

Example

$$g(x, y) = \Pi(x)\Pi(y)$$

$$G(k_x, k_y) = \text{sinc}(k_x)\text{sinc}(k_y)$$

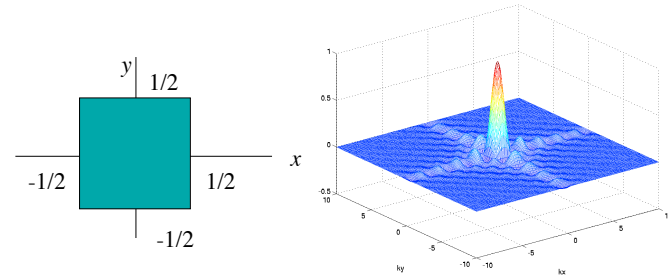
TT Liu, BE280A, UCSD Fall 2015

Example (sinc/rect)

Example

$$g(x, y) = \Pi(x)\Pi(y)$$

$$G(k_x, k_y) = \text{sinc}(k_x)\text{sinc}(k_y)$$



TT Liu, BE280A, UCSD Fall 2015

Examples

Is this function separable?
What is its Fourier Transform?

$$g(x, y) = \exp(-j2\pi(8x + 9y))\sin(28\pi x)$$

Pollev.com/be280a

TT Liu, BE280A, UCSD Fall 2015

Examples

$$g(x, y) = \delta(x, y) = \delta(x)\delta(y)$$

$$G(k_x, k_y) = 1$$

$$g(x, y) = \delta(x)$$

$$G(k_x, k_y) = \delta(k_y) !!!$$

TT Liu, BE280A, UCSD Fall 2015