

Bioengineering 280A  
Principles of Biomedical Imaging

Fall Quarter 2015  
MRI Lecture 1

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## Spin

- Intrinsic angular momentum of elementary particles -- electrons, protons, neutrons.
- Spin is quantized. Key concept in Quantum Mechanics.

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### Magnetic Moment and Angular Momentum



A charged sphere spinning about its axis has angular momentum and a magnetic moment.

This is a classical analogy that is useful for understanding quantum spin, but remember that it is only an analogy!

Relation:  $\mu = \gamma S$  where  $\gamma$  is the gyromagnetic ratio and  $S$  is the spin angular momentum.

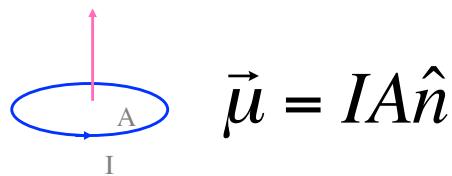
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### Nuclear Spin Rules

Number of Protons	Number of Neutrons	Spin	Examples
Even	Even	0	$^{12}\text{C}$ , $^{16}\text{O}$
Even	Odd	$j/2$	$^{17}\text{O}$
Odd	Even	$j/2$	$^1\text{H}$ , $^{23}\text{Na}$ , $^{31}\text{P}$
Odd	Odd	$j$	$^2\text{H}$

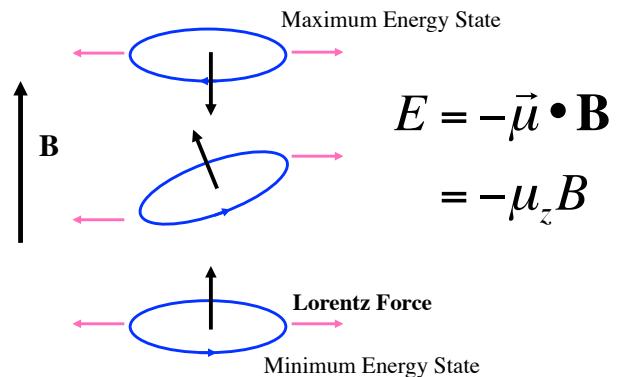
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## Classical Magnetic Moment


$$\vec{\mu} = IA\hat{n}$$

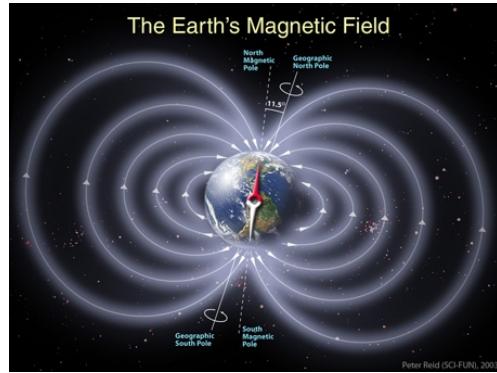
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## Energy in a Magnetic Field



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## Energy in a Magnetic Field



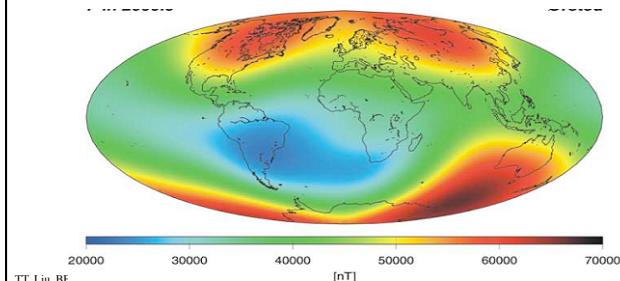
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## Magnetic Field Units

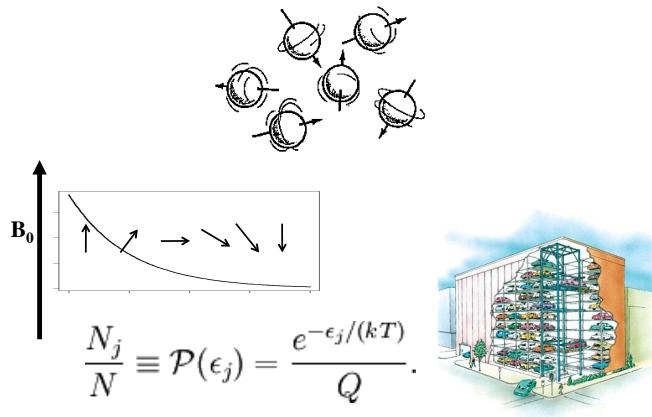
1 Tesla = 10,000 Gauss

Earth's field is about 0.5 Gauss

0.5 Gauss =  $0.5 \times 10^{-4}$  T =  $50 \mu\text{T}$

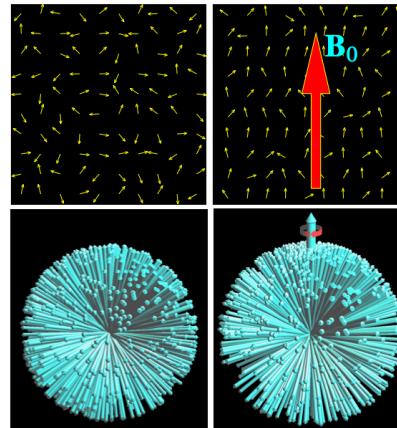


## Boltzmann Distribution



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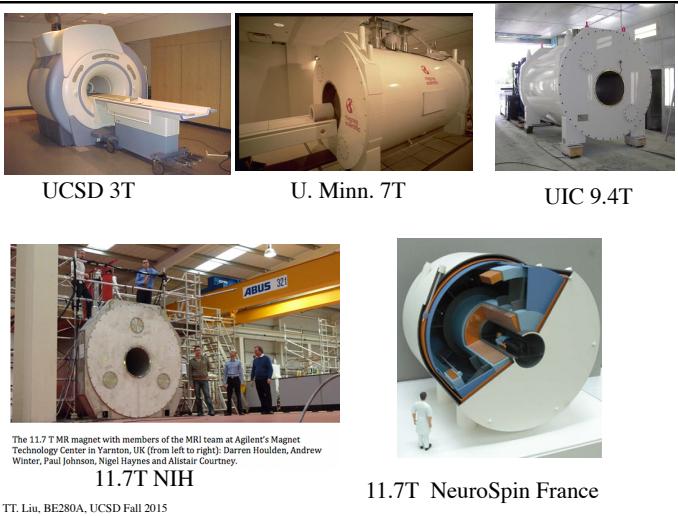
## Equilibrium Magnetization



$$\begin{aligned}\mathbf{M}_0 &= N \langle \mu_z \rangle \\ &\approx N \mu_z^2 B / (kT) \\ &= N \gamma^2 \hbar^2 B / (4kT)\end{aligned}$$

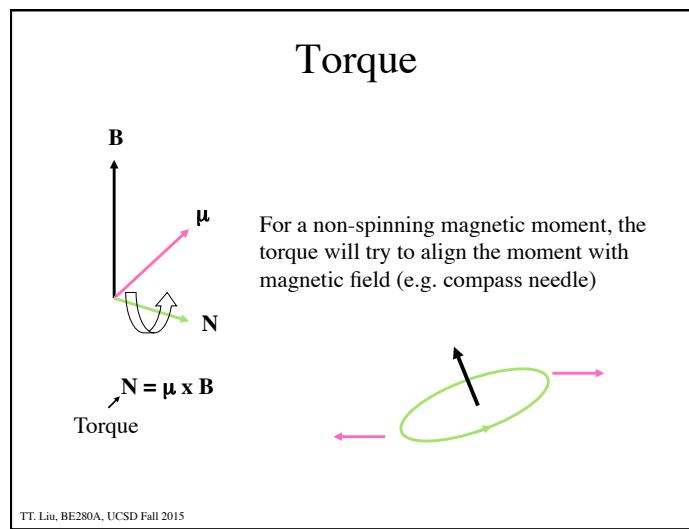
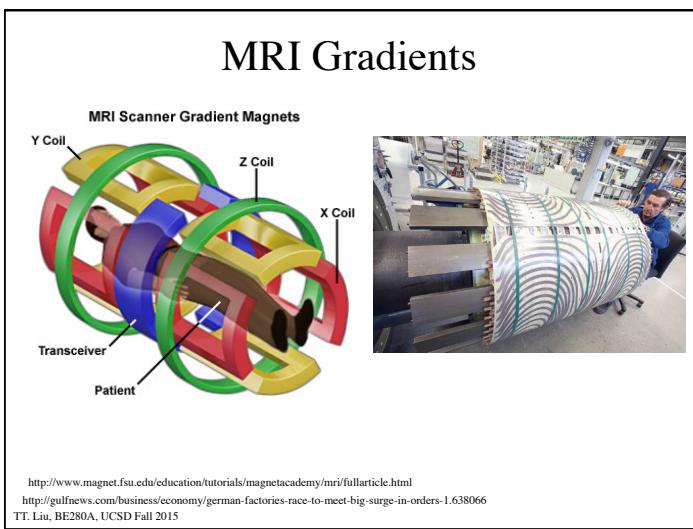
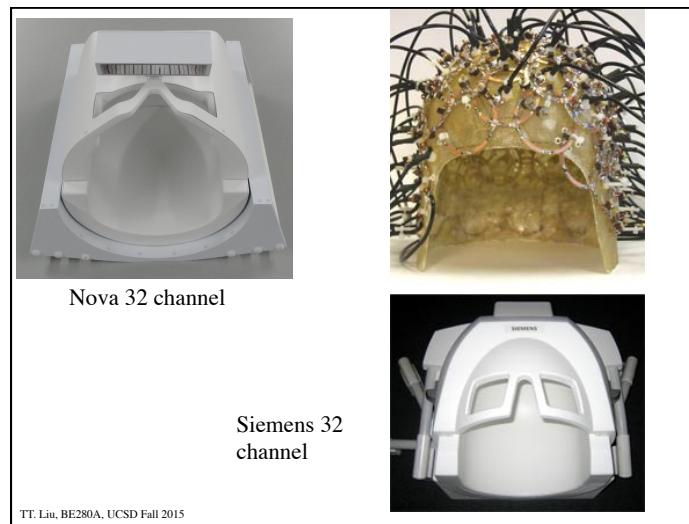
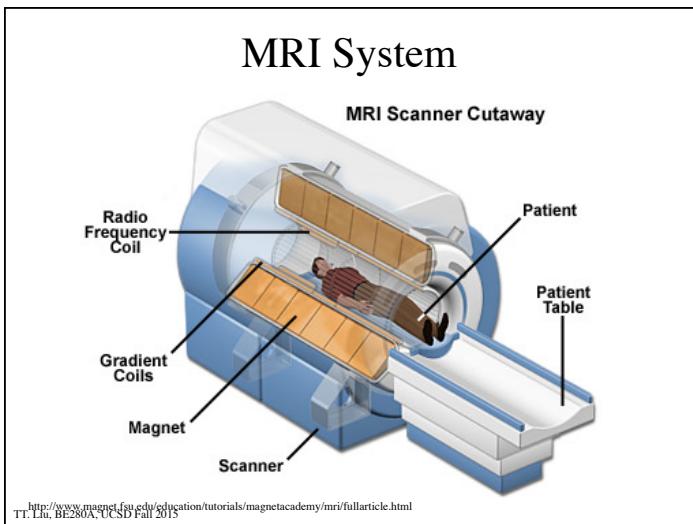
$N$  = number of nuclear spins per unit volume  
Magnetization is proportional to applied field.

Hansen 2009



***MRI Safety:  
The Invisible Force***

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## Precession

$$\text{Torque} \quad \mathbf{N} = \mu \times \mathbf{B}$$

$$\frac{d\mathbf{S}}{dt} = \mathbf{N}$$

Change in  
Angular momentum

$$\frac{d\mathbf{S}}{dt} = \mu \times \mathbf{B}$$

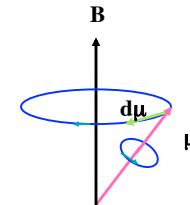
$$\mu = \gamma \mathbf{S}$$

Relation between  
magnetic moment and  
angular momentum

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## Precession

$$\frac{d\mu}{dt} = \mu \times \gamma \mathbf{B}$$



Analogous to motion of a gyroscope

Precesses at an angular frequency of

$$\omega = \gamma B$$

This is known as the **Larmor** frequency.



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## Notation and Units

1 Tesla = 10,000 Gauss

Earth's field is about 0.5 Gauss

0.5 Gauss =  $0.5 \times 10^{-4}$  T = 50  $\mu$ T

$\gamma = 26752$  radians/second/Gauss

$\gamma = \gamma / 2\pi = 4258$  Hz/Gauss

= 42.58 MHz/Tesla

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## Gyromagnetic Ratios

Nucleus	Spin	Magnetic Moment	$\gamma/(2\pi)$ (MHz/Tesla)	Abundance
<sup>1</sup> H	1/2	2.793	42.58	88 M
<sup>23</sup> Na	3/2	2.216	11.27	80 mM
<sup>31</sup> P	1/2	1.131	17.25	75 mM

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Source: Haacke et al., p. 27

## Larmor Frequency

$$\omega = \gamma \mathbf{B}$$

Angular frequency in rad/sec

$$f = \gamma \mathbf{B} / (2\pi)$$

Frequency in cycles/sec or Hertz,  
Abbreviated Hz

For a 1.5 T system, the Larmor frequency is 63.86 MHz which is 63.86 million cycles per second. For comparison, KPBS-FM transmits at 89.5 MHz.

Note that the earth's magnetic field is about 50  $\mu\text{T}$ , so that a 1.5T system is about 30,000 times stronger.

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## Magnetization Vector

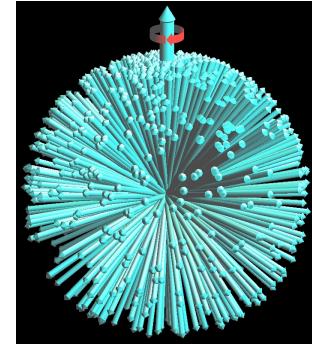
Vector sum of the magnetic moments over a volume.

For a sample at equilibrium in a magnetic field, the transverse components of the moments cancel out, so that there is only a longitudinal component.

Equation of motion is the same form as for individual moments.

$$\mathbf{M} = \frac{1}{V} \sum_{\text{protons in } V} \mu_i$$

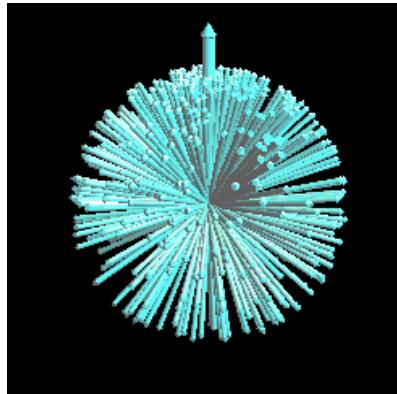
$$\frac{d\mathbf{M}}{dt} = \gamma \mathbf{M} \times \mathbf{B}$$



Hansen 2009

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## RF Excitation



<http://www.drcmr.dk/main/content/view/213/74/>

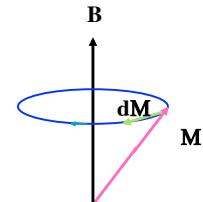
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## Free precession about static field

$$\frac{d\mathbf{M}}{dt} = \mathbf{M} \times \gamma \mathbf{B}$$

$$= \gamma \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ M_x & M_y & M_z \\ B_x & B_y & B_z \end{vmatrix}$$

$$= \gamma \begin{pmatrix} \hat{i}(B_z M_y - B_y M_z) \\ -\hat{j}(B_z M_x - B_x M_z) \\ \hat{k}(B_y M_x - B_x M_y) \end{pmatrix}$$



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## Free precession about static field

$$\begin{bmatrix} dM_x/dt \\ dM_y/dt \\ dM_z/dt \end{bmatrix} = \gamma \begin{bmatrix} B_z M_y - B_y M_z \\ B_x M_z - B_z M_x \\ B_y M_x - B_x M_y \end{bmatrix}$$

$$= \gamma \begin{bmatrix} 0 & B_z & -B_y \\ -B_z & 0 & B_x \\ B_y & -B_x & 0 \end{bmatrix} \begin{bmatrix} M_x \\ M_y \\ M_z \end{bmatrix}$$

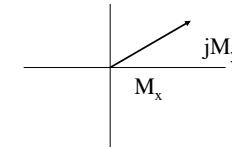
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## Precession

$$\begin{bmatrix} dM_x/dt \\ dM_y/dt \\ dM_z/dt \end{bmatrix} = \gamma \begin{bmatrix} 0 & B_0 & 0 \\ -B_0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} M_x \\ M_y \\ M_z \end{bmatrix}$$

Useful to define  $M = M_x + jM_y$

$$\begin{aligned} dM/dt &= d/dt(M_x + iM_y) \\ &= -j\gamma B_0 M \end{aligned}$$



Solution is a time-varying phasor

$$M(t) = M(0)e^{-j\gamma B_0 t} = M(0)e^{-j\omega_0 t}$$

Question: which way does this rotate with time?

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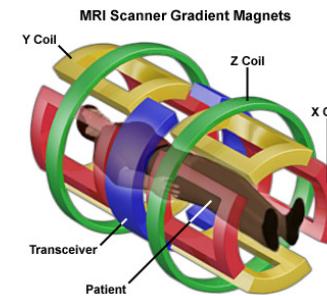
## Gradients

Spins precess at the Larmor frequency, which is proportional to the local magnetic field. In a constant magnetic field  $B_z=B_0$ , all the spins precess at the same frequency (ignoring chemical shift).

Gradient coils are used to add a spatial variation to  $B_z$  such that  $B_z(x,y,z) = B_0 + \Delta B_z(x,y,z)$ . Thus, spins at different physical locations will precess at different frequencies.

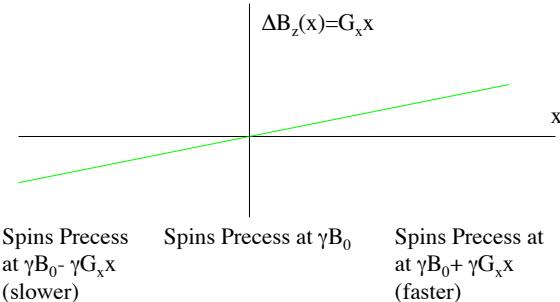
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## MRI Gradients



<http://www.magnet.fsu.edu/education/tutorials/magnetacademy/mri/fullarticle.html>  
<http://gulfnews.com/business/economy/german-factories-race-to-meet-big-surge-in-orders-1.638066>

## Interpretation



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## Rotating Frame of Reference

Reference everything to the magnetic field at isocenter.



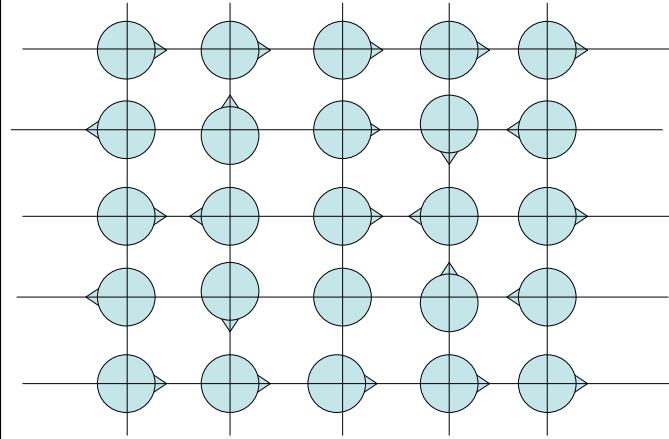
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## Spins

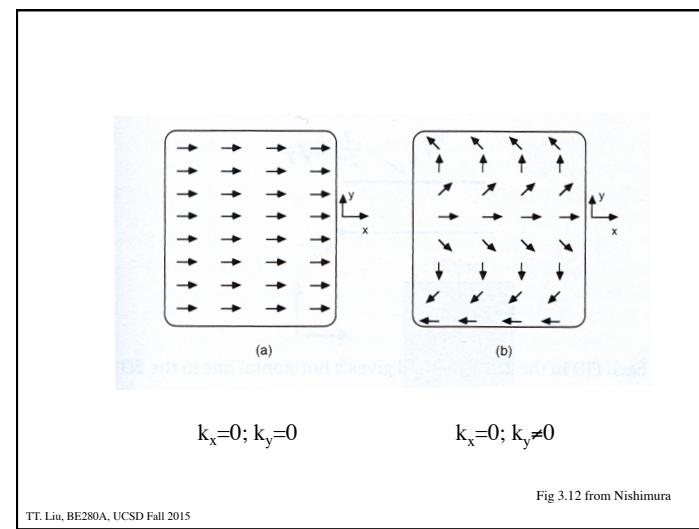
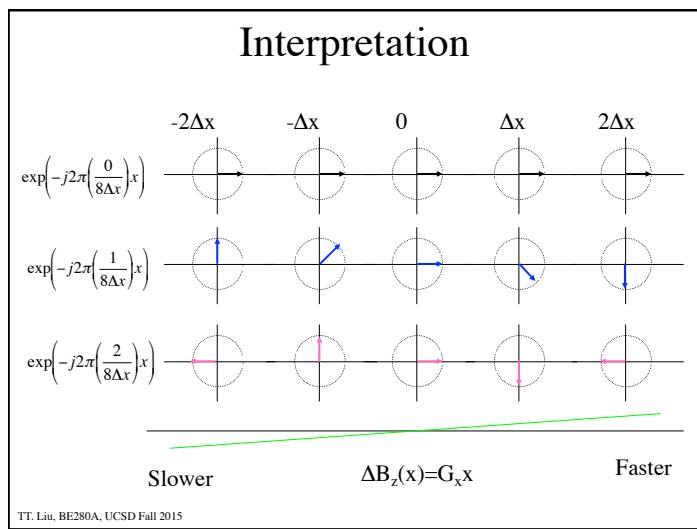
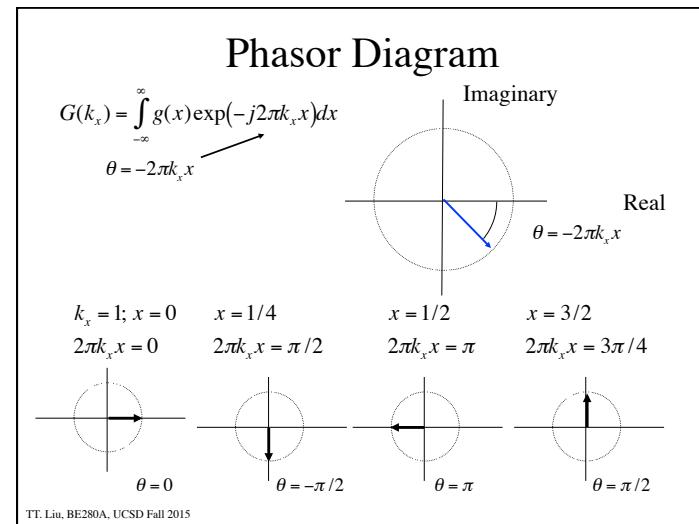
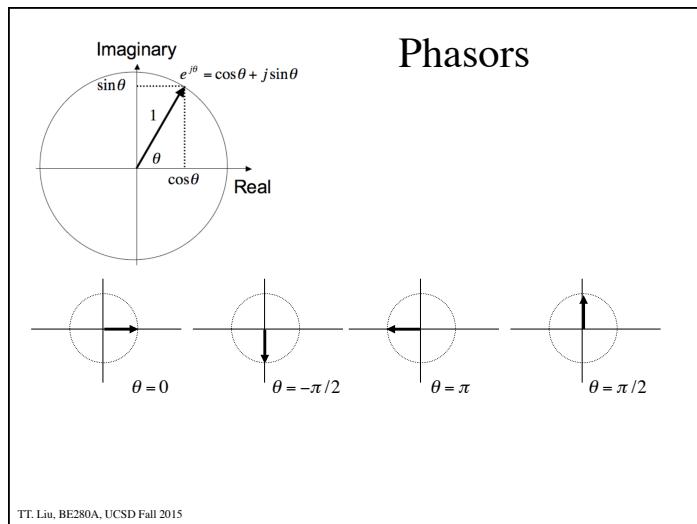


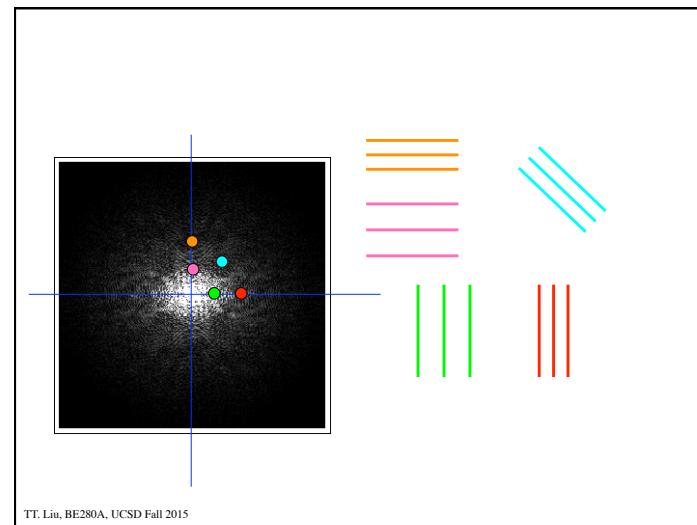
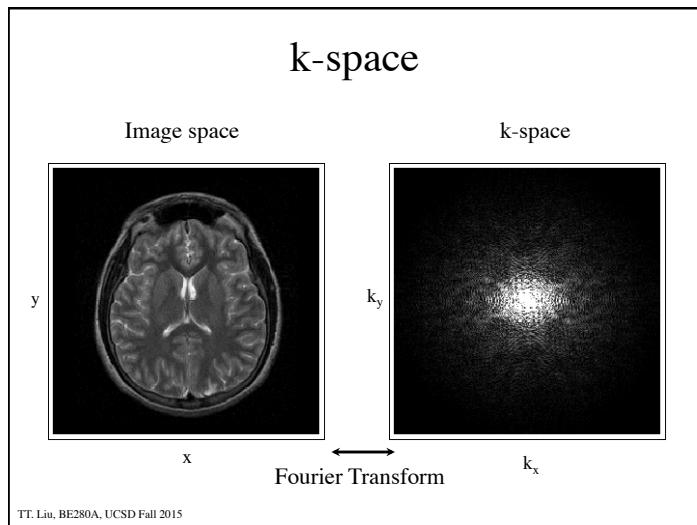
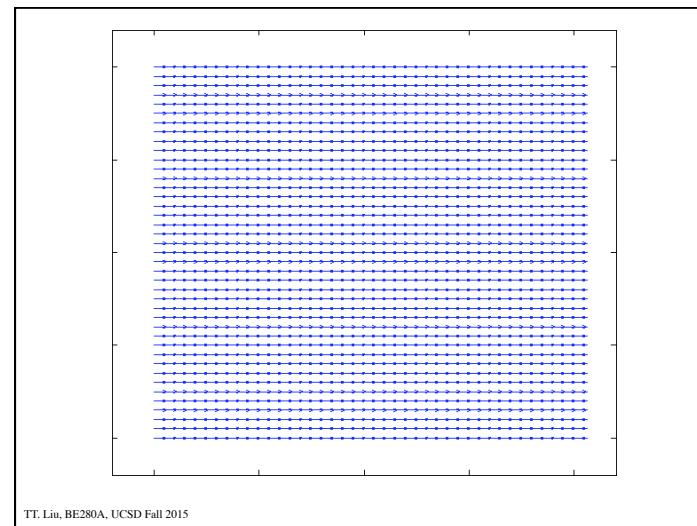
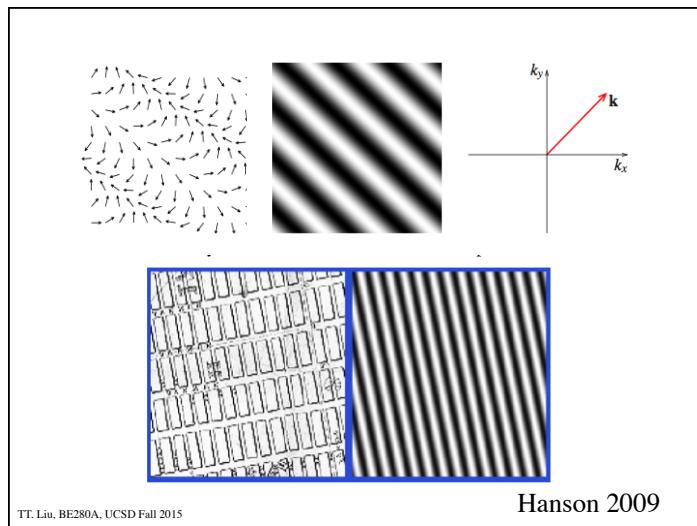
*There is nothing that nuclear spins will not do for you, as long as you treat them as human beings.*  
Erwin Hahn

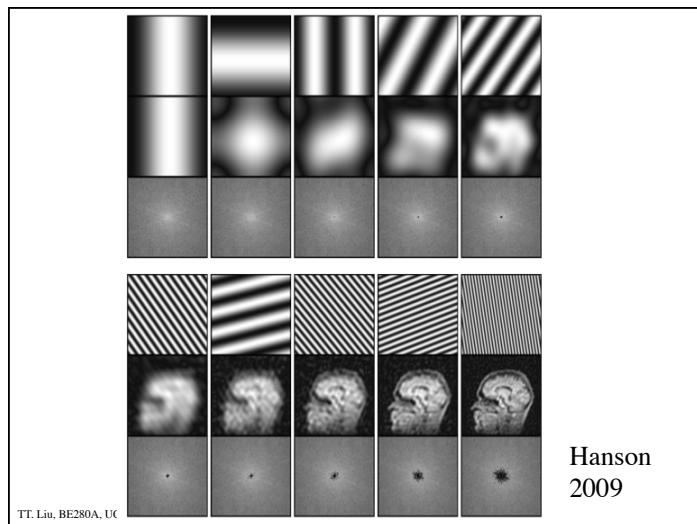
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## 2D Fourier Transform

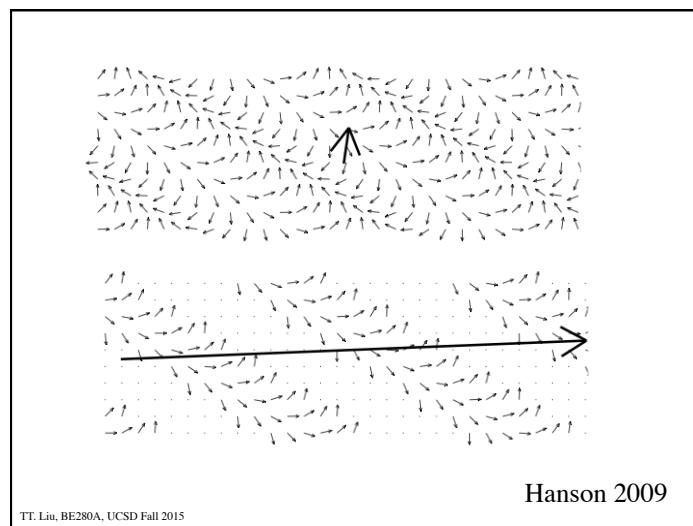
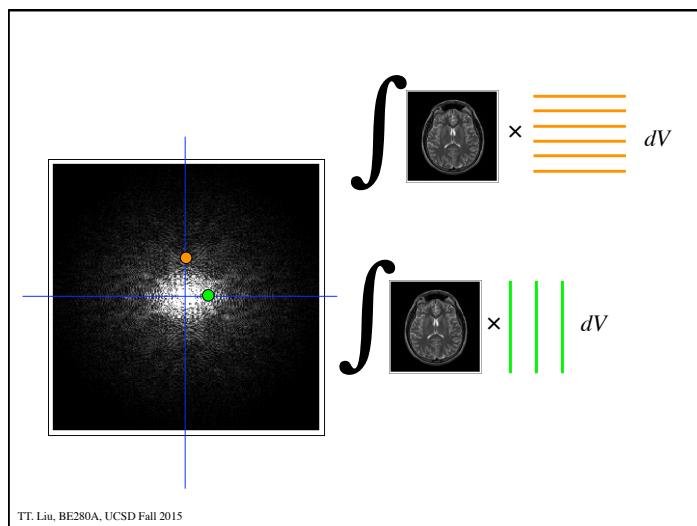
Fourier Transform

$$G(k_x, k_y) = F[g(x, y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) e^{-j2\pi(k_x x + k_y y)} dx dy$$

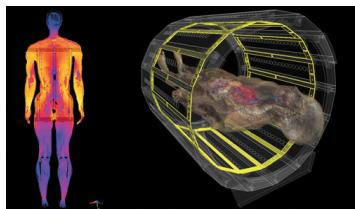
Inverse Fourier Transform

$$g(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} G(k_x, k_y) e^{j2\pi(k_x x + k_y y)} dk_x dk_y$$

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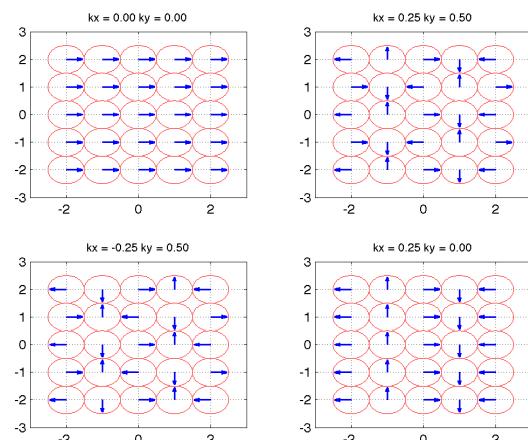
## Integration of the signal



[http://www.microwavejournal.com/legacy\\_assets/images/7842\\_Figure2.jpg](http://www.microwavejournal.com/legacy_assets/images/7842_Figure2.jpg)

[http://www.healthcare.philips.com/pwc\\_hc/main/shared/Assets/Images/MRI/coils/oa\\_coils\\_main\\_en.jpg](http://www.healthcare.philips.com/pwc_hc/main/shared/Assets/Images/MRI/coils/oa_coils_main_en.jpg)

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